Quantum limit for two-dimensional resolution of two incoherent optical point sources

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We obtain the multiple-parameter quantum Cramér-Rao bound for estimating the transverse Cartesian components of the centroid and separation of two incoherent optical point sources using an imaging system with finite spatial bandwidth. Under quite general and realistic assumptions on the point-spread function of the imaging system, and for weak source strengths, we show that the Cramér-Rao bounds for the x and y components of the separation are independent of the values of those components, which may be well below the conventional Rayleigh resolution limit. We also propose two linear-optics-based measurement methods that approach the quantum bound for the estimation of the Cartesian components of the separation once the centroid has been located. One of the methods is an interferometric scheme that approaches the quantum bound for sub-Rayleigh separations. The other method using fiber coupling can, in principle, attain the bound regardless of the distance between the two sources.

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I. INTRODUCTION

Rayleigh's criterion for resolution of two incoherent point sources [1] has been the most widely accepted criterion for optical resolution since its formulation in 1879. Being rooted in the optical measurement technology of its era, Rayleigh's criterion neglects the discrete and stochastic nature of the photodetection process. By adopting a stochastic framework, the studies [2–4] gave a modern formulation of the criterion for two sources radiating independently and incoherently. Using the Cramér-Rao (CR) bound of classical estimation theory [5], they showed that the localization accuracy of any unbiased estimator based on image-plane photon counting deteriorates rapidly on approaching sub-Rayleigh separations.

In the past few decades, advances in far-field superresolution techniques in microscopy [6–8] (see Ref. [9] for a review) have enabled us to sidestep Rayleigh's limit. Still, as they require that nearby sources are not emitting at the same time, those technologies do not challenge Rayleigh's criterion fundamentally for independently emitting sources.

Very recently, the localization problem was reconsidered from the perspective of quantum estimation theory using the quantum Cramér-Rao (QCR) bound [10-12]. Following a preliminary study of the fundamental localization limit for coherent sources in Ref. [13], Tsang et al. [14] obtained the quantum limit on localizing two weak incoherent optical point sources in one-dimensional imaging. Their quantum bound for estimating the separation between the sources is independent of that separation and shows no deterioration when the two sources are closer than the conventional Rayleigh limit of the imaging system. Similar conclusions were reproduced using a semiclassical photodetection theory under a Poisson model [15]. In Ref. [14], a linear optical measurement—spatial-mode demultiplexing (SPADE)—was also proposed and shown to attain the QCR bound for any separation. Another measurement scheme—superlocalization by image inversion interferometry (SLIVER)—was proposed in Ref. [16] that approaches the QCR bound for sub-Rayleigh separations. Recent experimental work [17-20] inspired by the above proposals has substantiated the surprising findings of the above papers.

In further theoretical work, the QCR bound on the onedimensional separation was calculated for thermal sources of arbitrary strength using a Gaussian-state model, and variants of SPADE and SLIVER were shown to approach the quantum limit over arbitrarily large ranges of the separation [21]. In Ref. [22], the question of optimizing the quantum state of the source pair under an energy constraint was addressed and the optimum source states for sub-Rayleigh imaging were found. In Ref. [23], a systematic approach to finding optimal measurement modes in the image plane for a given point-spread function was developed—see also [24]. In [25], the estimation of more general image parameters was studied, and in Refs. [26,27], the resolution problem was addressed in terms of quantum detection theory.

In this paper, we address the problem of two-dimensional resolution, i.e., complete transverse-plane localization of two incoherent optical point sources. Adopting the weak-source model of Ref. [14], we first obtain the full four-parameter quantum Fisher information (QFI) matrix characterizing the ultimate precision of estimating all four transverse Cartesian coordinates of the two sources. As in the one-dimensional case, the quantum bound suggests that the Rayleigh resolution limit is not fundamental and can be circumvented by an appropriate quantum measurement. We then focus on estimating the xand y components of the separation in the transverse plane once the centroid (midpoint) of the sources has been located. Recent theoretical studies in quantum parameter estimation have established the existence of a quantum measurement, mathematically represented by a positive operator-valued measure (POVM) [10,11] that achieves the QCR bound for estimation of a *single* parameter [28,29], while the quantum bound may not be attainable for two or more parameters. Here we propose two measurement schemes which asymptotically attain the QCR bound for both components of the separation over many repetitions. The first is based on the SLIVER scheme of Refs. [16,21] and approaches the QCR bound for small values of source separation. The second is a two-dimensional version of the SPADE scheme of Ref. [14] that, in principle, attains the bound regardless of the distance between the two sources.

This paper is organized as follows. In Sec. II, we describe the source and system model used in this paper. In Sec. III, we review the theory of the multiparameter QCR bound and evaluate it to obtain the fundamental limit for the estimation of the Cartesian components of the centroid and separation of the sources. In Secs. IV A and IV B, the SLIVER and SPADE schemes for estimating the components of the separation are detailed, and their Fisher information (FI) matrices are obtained. In Sec. V, we study the performance of the two schemes using Monte Carlo simulations, and close with concluding remarks in Sec. VI.

II. SOURCE AND SYSTEM MODEL

We first lay out the source and imaging system model used in this paper, the former being identical to that in Ref. [14]. We assume that two incoherent optical point sources with equal intensities are located on the object plane. Far-field radiation from these sources is collected at the entrance pupil of an optical imaging system such as a microscope or telescope. We assume that the paraxial approximation is valid for the field propagation from object plane to entrance pupil and consider a single polarization only. We further assume that the radiation from the sources is quasimonochromatic and excites only a single temporal mode in order to focus on the spatial aspects of the resolution problem. We assume also that the image-plane coordinates (x,y) have been rescaled by the magnification factor and that the imaging system is spatially invariant—these assumptions entail no essential loss of generality [30]. Under these conditions, the imaging system is described by its two-dimensional (possibly complex-valued) point-spread function (PSF) $\psi(x,y)$, satisfying the normalization condition $\int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy |\psi_s(x,y)|^2 = 1$ on the image

We are given two incoherent optical point sources with equal intensities located at coordinates (X_1, Y_1) and (X_2, Y_2) on the object plane. We assume the two sources are such that the probabilities that a single photon emitted by either source arrives at the image plane are equal and given by

$$\epsilon/2 \ll 1.$$
 (1)

We further assume that the probability of more than one photon arriving at the image plane is negligible. Under the above assumptions, the quantum density operator of the optical field on the image plane can be written as [14]

$$\rho = (1 - \epsilon)|\operatorname{vac}\rangle\langle\operatorname{vac}| + \frac{\epsilon}{2}(|\psi_1\rangle\langle\psi_1| + |\psi_2\rangle\langle\psi_2|), \qquad (2)$$

where $|\text{vac}\rangle$ denotes the vacuum state and the states $\{|\psi_s\rangle\}_{s=1}^2$ are given by

$$|\psi_s\rangle = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \psi_s(x, y) |x, y\rangle, \quad s = 1, 2, \quad (3)$$

with the wave functions

$$\psi_s(x, y) = \psi(x - X_s, y - Y_s), \quad s = 1, 2,$$
 (4)

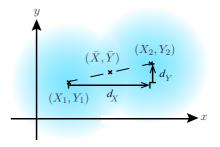


FIG. 1. An illustration of the focused image in the image plane of two point sources centered at (X_1, Y_1) and (X_2, Y_2) . The shading indicates the approximate extent of the PSF.

where $|x,y\rangle$ denotes the state with one photon in the mode corresponding to position (x,y) alone such that $\langle x,y|x',y'\rangle = \delta(x-x')\delta(y-y')$.

Equation (2) means that a photon arrives with equal probability $\epsilon/2$ from either of the two sources. If a photon arrives from the first source, it is in the state $|\psi_1\rangle$ with wave function $\psi_1(x,y)$; if it comes from the other source, it is in state $|\psi_2\rangle$ with wave function $\psi_2(x,y)$. The two states are not orthogonal in general and have the overlap

$$\delta \equiv \langle \psi_1 | \psi_2 \rangle = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \ \psi_1^*(x, y) \psi_2(x, y) \neq 0. \quad (5)$$

We also make a realistic simplifying assumption on the PSF $\psi(x,y)$ of the imaging system, namely that it is symmetric about the origin (or inversion symmetric), viz.,

$$\psi(x, y) = \psi(-x, -y), \tag{6}$$

for all x and y. This assumption is satisfied for most imaging systems of interest, including spatially invariant systems whose entrance aperture is rectangular or (hard or apodized) circular in shape [30], and is more general than the assumption of a circularly symmetric PSF used in Ref. [16]. Under this assumption, the overlap δ of Eq. (5) is real valued (see Appendix A).

The parameters we are interested in estimating are the four components of the vector,

$$\theta \equiv (\bar{X}, \bar{Y}, d_X, d_Y)^\top, \tag{7}$$

consisting of the centroid vector

$$(\bar{X}, \bar{Y}) \equiv [(X_1, Y_1) + (X_2, Y_2)]/2,$$
 (8)

and the separation vector

$$(d_X, d_Y) \equiv (X_2, Y_2) - (X_1, Y_1), \tag{9}$$

as depicted in Fig. 1.

III. THE QUANTUM LIMIT ON TWO-SOURCE LOCALIZATION

A. Review of the multiparameter quantum Cramér-Rao (QCR) bound

Let ρ_{θ} be the density operator of a quantum system depending on an unknown vector parameter θ . Consider the estimation of θ from the quantum measurement outcome \mathcal{Y} on

M copies of ρ_{θ} . The probability distribution of \mathcal{Y} is given by

$$P(\mathcal{Y}) = \operatorname{tr}[F(\mathcal{Y})\rho_{\theta}^{\otimes M}],\tag{10}$$

where $\{F(\mathcal{Y})\}$ is the positive operator-valued measure (POVM) that characterizes the statistics of the quantum measurement [10,31]. For any estimate $\check{\theta}(\mathcal{Y})$ of θ from the measurement outcome, the estimation error covariance matrix has the matrix elements

$$\Sigma_{\mu\nu} \equiv \mathbb{E}\{ [\check{\theta}_{\mu}(\mathcal{Y}) - \theta_{\mu}] [\check{\theta}_{\nu}(\mathcal{Y}) - \theta_{\nu}] \}, \tag{11}$$

where $\mathbb{E}[z(\mathcal{Y})]$ of an arbitrary function $z(\mathcal{Y})$ of the measurement outcome is the statistical expectation,

$$\mathbb{E}[z(\mathcal{Y})] \equiv \int d\mathcal{Y} P(\mathcal{Y}) z(\mathcal{Y}). \tag{12}$$

For any unbiased estimator, defined as one for which

$$\mathbb{E}[\check{\theta}(\mathcal{Y}) - \theta] = 0, \tag{13}$$

the error covariance matrix Σ is bounded by the classical and quantum Cramér-Rao bounds [5,10–12],

$$\Sigma \geqslant \mathcal{J}^{-1} \geqslant \mathcal{K}^{-1}.\tag{14}$$

Here, the inequalities mean that matrices $\Sigma - \mathcal{J}^{-1}$, $\Sigma - \mathcal{K}^{-1}$, and $\mathcal{J}^{-1} - \mathcal{K}^{-1}$ are positive semidefinite. Matrix \mathcal{J} is the *classical* Fisher information (FI) matrix with entries

$$\mathcal{J}_{\mu\nu} = \mathbb{E}\left\{ \left[\frac{\partial}{\partial \theta_{\mu}} \ln P(\mathcal{Y}) \right] \left[\frac{\partial}{\partial \theta_{\nu}} \ln P(\mathcal{Y}) \right] \right\}, \quad (15)$$

and matrix K is the quantum Fisher information (QFI) matrix which can be expressed in terms of the so-called symmetric logarithmic derivative (SLD) operators $\{\mathcal{L}_{u}\}$ as

$$\mathcal{K}_{\mu\nu} = M \operatorname{tr} \frac{\mathcal{L}_{\mu} \mathcal{L}_{\nu} + \mathcal{L}_{\nu} \mathcal{L}_{\mu}}{2} \rho_{\theta}. \tag{16}$$

If ρ_{θ} is diagonalized in an orthogonal basis { $|e_n\rangle$ }, viz., $\rho_{\theta} = \sum_n D_n |e_n\rangle\langle e_n|$, \mathcal{L}_{μ} can be expressed as [12,32]

$$\mathcal{L}_{\mu} = \sum_{\substack{m,n \\ D_m + D_n \neq 0}} \frac{2}{D_m + D_n} \langle e_m | \frac{\partial \rho_{\theta}}{\partial \theta_{\mu}} | e_n \rangle | e_m \rangle \langle e_n |. \tag{17}$$

B. Quantum Fisher information (QFI) matrix for two-source localization

We now consider the problem of estimation of the centroid and separation vectors for two incoherent point sources under the model of Sec. II. Assuming the quantum density operator of Eq. (2) and the inversion symmetry of the PSF [viz., Eq. (6)], the SLD operators of Eq. (17) and the QFI matrix \mathcal{K} of Eq. (16) can be explicitly evaluated. The salient details of the derivation of \mathcal{K} are relegated to Appendix A, namely, the basis $\{|e_n\rangle\}$ in which ρ is diagonal, its eigenvalues $\{D_n\}$, and the SLD operators. The QFI matrix in terms of θ defined in Eq. (7) is found to be

$$\mathcal{K} = N \begin{pmatrix} 4(\Delta k_X^2 - \gamma_X^2) & 4(\alpha - \gamma_X \gamma_Y) & 0 & 0\\ 4(\alpha - \gamma_X \gamma_Y) & 4(\Delta k_Y^2 - \gamma_Y^2) & 0 & 0\\ 0 & 0 & \Delta k_X^2 & \alpha\\ 0 & 0 & \alpha & \Delta k_Y^2 \end{pmatrix},$$
(18)

where $N = M\epsilon$ is the average photon number collected over M trials, and

$$\Delta k_X^2 \equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \left| \frac{\partial \psi(x, y)}{\partial x} \right|^2,$$

$$\Delta k_Y^2 \equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \left| \frac{\partial \psi(x, y)}{\partial y} \right|^2,$$

$$\gamma_X \equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \psi^*(x - d_X, y - d_Y) \frac{\partial \psi(x, y)}{\partial x},$$

$$\gamma_Y \equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \psi^*(x - d_X, y - d_Y) \frac{\partial \psi(x, y)}{\partial y},$$

$$\alpha = \text{Re} \left[\int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \frac{\partial \psi^*(x, y)}{\partial x} \frac{\partial \psi(x, y)}{\partial y} \right], \quad (19)$$

for Re(z) denoting the real part of z. The quantities Δk_X and Δk_Y are related to the spatial spectral width of the PSF in the x and y direction, respectively, and, along with α , are independent of the source parameters θ . γ_X and γ_Y depend on the separation coordinates (d_X, d_Y) , but not on the centroid coordinates (\bar{X}, \bar{Y}) . Thus, \mathcal{K} as a whole is independent of (\bar{X}, \bar{Y}) , as may be expected from our assumption of a spatially invariant imaging system. Note that \mathcal{K} has a block-diagonal form with respect to the centroid and separation coordinate pairs, and that the matrix elements related to the estimation errors of separations d_X and d_Y — \mathcal{K}_{33} and \mathcal{K}_{44} —are independent of (d_X, d_Y) as well.

The QFI matrix can be simplified further for the case of a PSF $\psi(x,y)$ with reflection symmetry about the x and y axes, viz..

$$\psi(x,y) = \psi(x,-y) = \psi(-x,-y),$$
 (20)

which is also a sufficient condition for symmetry about the origin [Eq. (6)]. Under this condition, the quantity α of Eq. (19) vanishes as its integrand satisfies

$$\frac{\partial \psi^*(x,y)}{\partial x} \frac{\partial \psi(x,y)}{\partial y} = -\frac{\partial \psi^*(x,-y)}{\partial x} \frac{\partial \psi(x,-y)}{\partial y}$$
(21)

for all x, y; hence, the integral goes to zero. The Fisher information matrix K becomes

$$\mathcal{K} = N \begin{pmatrix} 4(\Delta k_X^2 - \gamma_X^2) & -4\gamma_X \gamma_Y & 0 & 0\\ -4\gamma_X \gamma_Y & 4(\Delta k^2 - \gamma_Y^2) & 0 & 0\\ 0 & 0 & \Delta k_X^2 & 0\\ 0 & 0 & 0 & \Delta k_Y^2 \end{pmatrix}.$$
(22)

Note that a circularly symmetric $\psi(x,y)$ is a sufficient condition for the reflection symmetries. In that case, we have, additionally,

$$\Delta k_X = \Delta k_Y \equiv \Delta k. \tag{23}$$

C. Comparison to direct imaging

The QCR bound \mathcal{K}^{-1} can be compared with the classical CR bound for conventional direct imaging. For direct imaging using an ideal continuum photodetector in the image plane, the probability density of the position of arrival of the photon

is expressed in terms of the mean intensity as [14]

$$\Lambda(x,y) = \frac{1}{2} [|\psi_1(x,y)|^2 + |\psi_2(x,y)|^2], \tag{24}$$

such that the classical FI matrix

$$\mathcal{J}_{\mu\nu}^{(\text{dir})} = N \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{1}{\Lambda(x,y)} \frac{\partial \Lambda(x,y)}{\partial \theta_{\mu}} \frac{\partial \Lambda(x,y)}{\partial \theta_{\nu}}.$$
 (25)

For any PSF $\psi(x, y)$, let

$$I(x,y) \equiv |\psi(x,y)|^2 \tag{26}$$

be the intensity point-spread function. We assume that the centroid (\bar{X}, \bar{Y}) is located at the origin and we are only estimating the separation vector $\eta = (d_X, d_Y)^{\top}$. The mean intensity in Eq. (24) becomes

$$\Lambda(x,y) = \frac{1}{2} \left[I\left(x + \frac{d_X}{2}, y + \frac{d_Y}{2}\right) + I\left(x - \frac{d_X}{2}, y - \frac{d_Y}{2}\right) \right]. \tag{27}$$

For small values of d_X and d_Y , we can expand $\Lambda(x,y)$ to the second order to obtain

$$\Lambda(x,y) = I(x,y) + \frac{d_X^2}{8} \frac{\partial^2 I(x,y)}{\partial x^2} + \frac{d_X d_Y}{4} \frac{\partial^2 I(x,y)}{\partial x \partial y} + \frac{d_Y^2}{8} \frac{\partial^2 I(x,y)}{\partial y^2} + o(d^2),$$
(28)

where $o(d^2)$ denotes terms asymptotically smaller than d_X^2 , $d_X d_Y$, and d_Y^2 . Substituting this equation into Eq. (25) gives the Fisher information matrix $\mathcal{J}^{(\text{dir})}$. For a circularly symmetric PSF $\psi(x,y)$, the FI matrix in terms of η is

$$\mathcal{J}_{11}^{(\text{dir})} = \frac{N}{16} \left(d_X^2 \kappa_1 + d_Y^2 \kappa_2 \right) + o(d^2),
\mathcal{J}_{22}^{(\text{dir})} = \frac{N}{16} \left(d_X^2 \kappa_2 + d_Y^2 \kappa_1 \right) + o(d^2),
\mathcal{J}_{12}^{(\text{dir})} = \frac{N}{16} d_X d_Y (\kappa_1 + \kappa_2) + o(d^2),$$
(29)

where

$$\kappa_{1} = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{1}{I(x,y)} \left[\frac{\partial^{2} I(x,y)}{\partial x^{2}} \right]^{2}$$

$$= \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{1}{I(x,y)} \left[\frac{\partial^{2} I(x,y)}{\partial y^{2}} \right]^{2},$$

$$\kappa_{2} = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{1}{I(x,y)} \left[\frac{\partial^{2} I(x,y)}{\partial x \partial y} \right]^{2}.$$
(30)

For the direct-imaging method, the CR bound terms related to the estimation of separation d_X and d_Y are

$$\{[\mathcal{J}^{(\text{dir})}]^{-1}\}_{11} \approx \frac{16}{N} \frac{d_X^2 \kappa_2 + d_Y^2 \kappa_1}{(d_X^2 - d_Y^2)^2 \kappa_1 \kappa_2},$$
$$\{[\mathcal{J}^{(\text{dir})}]^{-1}\}_{22} \approx \frac{16}{N} \frac{d_X^2 \kappa_1 + d_Y^2 \kappa_2}{(d_X^2 - d_Y^2)^2 \kappa_1 \kappa_2},$$
(31)

which approach infinity as $d_X, d_Y \to 0$. For illustration, we assume a circular Gaussian PSF $\psi(x, y)$ of the form

$$\psi_G(x,y) = \left(\frac{1}{2\pi\sigma^2}\right)^{1/2} \exp\left(-\frac{x^2 + y^2}{4\sigma^2}\right),$$
 (32)

Cramér-Rao lower bounds

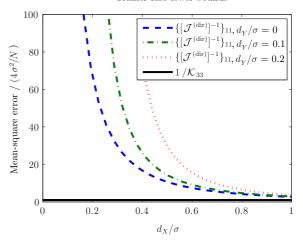


FIG. 2. Quantum $(1/K_{33})$ and classical $(\{[\mathcal{J}^{(dir)}]^{-1}\}_{11})$ CR bounds vs normalized separation d_X/σ for a circular Gaussian PSF of Eq. (32). The classical bounds are plotted for different values of $d_Y/\sigma = 0,0.1$, and 0.2. The bounds are normalized with respect to the quantum limit $4\sigma^2/N$.

such that its intensity point-spread function

$$I_G(x,y) = \frac{1}{2\pi\sigma^2} \exp\left(-\frac{x^2 + y^2}{2\sigma^2}\right).$$
 (33)

The PSF-dependent terms are now

$$\Delta k = \frac{1}{2\sigma}, \quad \kappa_1 = 6\kappa_2 = \frac{3}{2\sigma^2}, \tag{34}$$

and Eq. (31) becomes

$$\{[\mathcal{J}^{(\text{dir})}]^{-1}\}_{11} \approx \frac{4\sigma^2}{N} \frac{8(d_X/\sigma)^2 + 48(d_Y/\sigma)^2}{3[(d_X/\sigma)^2 - (d_Y/\sigma)^2]^2},$$
 (35)

$$\{[\mathcal{J}^{(\text{dir})}]^{-1}\}_{22} \approx \frac{4\sigma^2}{N} \frac{48(d_X/\sigma)^2 + 8(d_Y/\sigma)^2}{3[(d_X/\sigma)^2 - (d_Y/\sigma)^2]^2}.$$
 (36)

The QCR bound $1/\mathcal{K}_{33}$ of Eq. (22) and the CR bound $\{[\mathcal{J}^{(\text{dir})}]^{-1}\}_{11}$ of Eq. (35) for the estimation of d_X are plotted as a function of separation parameters d_X and d_Y in Fig. 2. The plot shows a huge divergence of the CR bound for the directimaging method from the quantum limit as d_X decreases. This implies that a considerable improvement can be obtained if a quantum-optimal measurement is implemented. As Eq. (36) is similar to Eq. (35) by interchanging the variables d_X and d_Y , the plot of the CR bound related to d_Y is identical to Fig. 2 and the same conclusion can be drawn for small values of d_Y .

In Sec. IV, we discuss concrete measurement schemes to simultaneously estimate the separation parameters $\eta = (d_X, d_Y)^{\top}$. For these schemes, we assume that the centroid vector (\bar{X}, \bar{Y}) has already been located and compare their performance to the quantum bound obtained in Sec. III B.

IV. LINEAR-OPTICS SCHEMES FOR ESTIMATING THE SEPARATION VECTOR

In this section, we give two linear-optics schemes for estimating the separation vector (d_X, d_Y) . In so doing, we assume that the centroid of the sources has already been

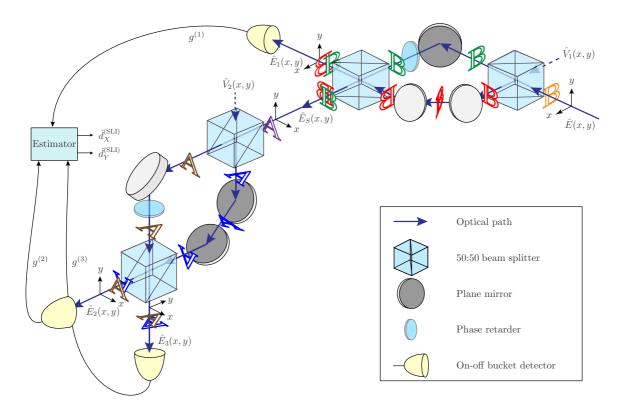


FIG. 3. A schematic of two-stage SLIVER. The image-plane field operator $\hat{E}(x,y)$ is split—with the appropriate contributions from the field operator $\hat{V}_1(x,y)$ input to the vacuum input port of the first beam splitter—into its symmetric $[\hat{E}_S(x,y)]$ and antisymmetric $[\hat{E}_1(x,y)]$ components with respect to reflection about the y axis. The $\hat{E}_1(x,y)$ component impinges upon a bucket photodetector. The $\hat{E}_S(x,y)$ component is separated again into symmetric $[\hat{E}_3(x,y)]$ and antisymmetric $[\hat{E}_2(x,y)]$ components with respect to reflection about the x axis, which are detected using bucket detectors. The set of binary outcomes, $g^{(1)}$, $g^{(2)}$, and $g^{(3)}$, observed in the detectors over a series of M measurements is processed to give estimates d_X and d_Y of the components of the separation. The required field transformations are realized by the extra reflection at an appropriately aligned plane mirror in one arm of the balanced Mach-Zehnder interferometers, which are indicated by the evolution of the letters \mathbb{A} and \mathbb{B} through the system.

located, perhaps by spatially resolved direct detection on a portion of the light reaching the image plane—see, e.g., the hybrid scheme of Ref. [14]. As is well known, unlike estimating the separation coordinates, locating the centroid coordinates with direct imaging is near quantum optimal [10,14]. Assuming that the centroid of the sources is imaged at the origin of image-plane coordinates, the images of the sources are centered at $\mp \frac{1}{2}(d_X, d_Y)$ in the image plane. The single-photon wave functions corresponding to the two sources then become

$$\psi_1(x,y) = \psi\left(x + \frac{d_X}{2}, y + \frac{d_Y}{2}\right),$$
 (37)

$$\psi_2(x,y) = \psi\left(x - \frac{d_X}{2}, y - \frac{d_Y}{2}\right).$$
 (38)

Our performance analysis of the schemes of this section—in particular, the derivation of their classical FI matrices—proceeds just as well if the two sources have unequal one-photon arrival probabilities ϵ_1 and ϵ_2 , which need not necessarily satisfy $\epsilon_1, \epsilon_2 \ll 1$. In this generalization of the source model of Sec. II, the image-plane density operator of Eq. (2) is replaced by

$$\rho = (1 - \epsilon_1 - \epsilon_2)|\text{vac}\rangle\langle\text{vac}| + \epsilon_1|\psi_1\rangle\langle\psi_1| + \epsilon_2|\psi_2\rangle\langle\psi_2|.$$
(39)

We denote the expected number of photons reaching the image plane by $\epsilon_{\text{tot}} = \epsilon_1 + \epsilon_2$.

A. The two-stage SLIVER scheme

We now propose a two-stage interferometric scheme for estimation of d_X and d_Y adapting the SLIVER schemes of Refs. [16,21]. In those works, a thermal source model was adopted for which the existence of a positive Glauber-Sudarshan P representation allowed an analysis in the framework of semiclassical photodetection theory [33,34]. The weak single-photon state of Eq. (39) does not possess a non-negative P representation, necessitating a fully quantum analysis that we carry out by propagating the field operators through the system in the Heisenberg picture.

We assume a PSF $\psi(x,y)$ with reflection symmetries about the x and y axes, viz., Eq. (20). The SLIVER scheme is illustrated in Fig. 3 and consists of two stages. Viewed semiclassically, the first stage involves the separation of the input field E(x,y) into its antisymmetric component [E(x,y)-E(-x,y)]/2 and its symmetric component [E(x,y)+E(-x,y)]/2 with respect to reflection about the y axis. These components can be obtained by splitting the input field E(x,y) using a 50-50 beam splitter, inverting the x coordinates of the field (i.e., reflecting the field about the y axis) in one output, and recombining the two beams at a second

50-50 beam splitter. The optics of this stage thus consists of a balanced Mach-Zehnder interferometer with an extra reflection at an appropriately aligned plane mirror in one arm.

In the quantum treatment, we replace the complex field amplitudes $E_{\alpha}(x,y)$ of each beam in any part of the system (indexed generically by α) with the corresponding field operators $\hat{E}_{\alpha}(x,y)$, which are required to satisfy the commutation rules [33,34],

$$[\hat{E}_{\alpha}(x,y),\hat{E}_{\beta}(x',y')] = 0,$$

$$[\hat{E}_{\alpha}(x,y),\hat{E}_{\beta}^{\dagger}(x',y')] = \delta_{\alpha\beta} \delta(x-x')\delta(y-y'). \tag{40}$$

Using the standard Heisenberg-picture treatment of the input-output relations of a beam splitter [33–35], the output field operators of the first stage of the SLIVER system are given by

$$\hat{E}_1(x,y) = \frac{1}{2} [\hat{E}(x,y) - \hat{E}(-x,y)] + \frac{1}{2} [\hat{V}_1(x,y) + \hat{V}_1(-x,y)],$$
(41)

$$\hat{E}_S(x,y) = \frac{1}{2} [\hat{E}(x,y) + \hat{E}(-x,y)] + \frac{1}{2} [\hat{V}_1(x,y) - \hat{V}_1(-x,y)],$$
(42)

where $\hat{V}_1(x,y)$ is the input field operator at the open port of the first beam splitter that must be included to preserve the commutator relations given by Eq. (40)—the field in this port is in the vacuum state. At the antisymmetric output port with the field operator of Eq. (41), an on-off non-spatially-resolving (bucket) detector is placed to distinguish between no photon and one photon. The measurement outcome, denoted $g^{(1)}$, is binary—zero if the detector does not click and one if it does.

In the second stage, the output beam $\hat{E}_S(x,y)$ of the symmetric port is used as input to a second interferometer, which similarly splits the field into antisymmetric $[\hat{E}_2(x,y)]$ and symmetric $[\hat{E}_3(x,y)]$ components with respect to reflection about the x axis. The output field operators of the second stage are given by

$$\hat{E}_{2}(x,y) = \frac{1}{2} [\hat{E}_{S}(x,y) - \hat{E}_{S}(x,-y)]$$

$$+ \frac{1}{2} [\hat{V}_{2}(x,y) + \hat{V}_{2}(x,-y)],$$

$$\hat{E}_{3}(x,y) = \frac{1}{2} [\hat{E}_{S}(x,y) + \hat{E}_{S}(x,-y)]$$

$$+ \frac{1}{2} [\hat{V}_{2}(x,y) - \hat{V}_{2}(x,-y)],$$
(44)

where $\hat{V}_2(x,y)$ is the input vacuum field operator at the open port of the first beam splitter of this stage. The output fields $\hat{E}_2(x,y)$ and $\hat{E}_3(x,y)$ of this stage impinge upon two on-off bucket detectors to give measurement outcomes $g^{(2)}$ and $g^{(3)}$, respectively. As in the previous stage, $g^{(2)}$ and $g^{(3)}$ take binary values—zero if the corresponding detector does not click and one if it does—which are recorded.

The expected photon number at the rth detector is given by $\operatorname{tr}(\rho \hat{N}_r)$, where the photon number operator in the rth output beam is given by

$$\hat{N}_r = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \ \hat{E}_r^{\dagger}(x, y) \hat{E}_r(x, y), \quad r = 1, 2, 3. \quad (45)$$

Since the state ρ of Eq. (39) has at most one photon, at most one photon will impinge upon the three photodetectors taken together. Therefore, there are only four mutually exclusive measurement outcomes—outcome "0" corresponds to the case where no photon is detected in any of the three detectors and outcome "r" corresponds to the case where only the rth detector clicks. The probabilities of these outcomes are

$$P(0) = \Pr[g^{(1)} = 0, g^{(2)} = 0, g^{(3)} = 0],$$

$$P(1) = \Pr[g^{(1)} = 1, g^{(2)} = 0, g^{(3)} = 0],$$

$$P(2) = \Pr[g^{(1)} = 0, g^{(2)} = 1, g^{(3)} = 0],$$

$$P(3) = \Pr[g^{(1)} = 0, g^{(2)} = 0, g^{(3)} = 1].$$
(46)

Since either zero or one photon arrives at each detector, the probability that the rth detector clicks is equal to the expected photon number at the rth detector, i.e.,

$$P(r) = \text{tr}(\rho \hat{N}_r), \quad r = 1, 2, 3,$$
 (47)

$$P(0) = 1 - \epsilon_{\text{tot}}.\tag{48}$$

The calculation of the above probabilities is detailed in Appendix B, with the following result:

$$P(1) = \frac{\epsilon_{\text{tot}}}{2} (1 - \delta_x),$$

$$P(2) = \frac{\epsilon_{\text{tot}}}{4} (1 + \delta_x - \delta_y - \delta),$$

$$P(3) = \frac{\epsilon_{\text{tot}}}{4} (1 + \delta_x + \delta_y + \delta),$$
(49)

where

$$\delta_x \equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \psi^*(x, y) \psi(x - d_X, y), \qquad (50)$$

$$\delta_y \equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \psi^*(x, y) \psi(x, y - d_Y), \qquad (51)$$

and δ is defined in Eq. (5).

The classical FI matrix $\mathcal{J}^{(\text{SLI})}$ for the separation vector $\eta = (d_X, d_Y)^{\top}$ using SLIVER has the following elements [cf. Eq. (15)]:

$$\mathcal{J}_{\mu\nu}^{(\text{SLI})} = \sum_{r=1}^{3} P(r) \frac{\partial \ln P(r)}{\partial \eta_{\mu}} \frac{\partial \ln P(r)}{\partial \eta_{\nu}}, \quad \mu, \nu = 1, 2. \quad (52)$$

Using Eqs. (52) and (49), we have

$$\mathcal{J}_{11}^{(\text{SLI})} = \frac{\epsilon_{\text{tot}}}{2} \left[\frac{1}{1 - \delta_x} \left(\frac{\partial \delta_x}{\partial d_X} \right)^2 + \frac{1}{2(1 + \delta_x - \delta_y - \delta)} \left(\frac{\partial \delta_x}{\partial d_X} - \frac{\partial \delta}{\partial d_X} \right)^2 + \frac{1}{2(1 + \delta_x + \delta_y + \delta)} \left(\frac{\partial \delta_x}{\partial d_X} + \frac{\partial \delta}{\partial d_X} \right)^2 \right],$$

$$\mathcal{J}_{22}^{(\text{SLI})} = \frac{\epsilon_{\text{tot}}}{4} \left[\frac{1}{1 + \delta_x - \delta_y - \delta} \left(\frac{\partial \delta_y}{\partial d_Y} + \frac{\partial \delta}{\partial d_Y} \right)^2 + \frac{1}{1 + \delta_x + \delta_y + \delta} \left(\frac{\partial \delta_y}{\partial d_Y} + \frac{\partial \delta}{\partial d_Y} \right)^2 \right],$$

$$\mathcal{J}_{12}^{(\text{SLI})} = \frac{\epsilon_{\text{tot}}}{4} \left[\frac{1}{1 + \delta_x + \delta_y + \delta} \left(\frac{\partial \delta_x}{\partial d_X} + \frac{\partial \delta}{\partial d_X} \right) \left(\frac{\partial \delta_y}{\partial d_Y} + \frac{\partial \delta}{\partial d_Y} \right) - \frac{1}{1 + \delta_x - \delta_y - \delta} \left(\frac{\partial \delta_x}{\partial d_X} - \frac{\partial \delta}{\partial d_X} \right) \left(\frac{\partial \delta_y}{\partial d_Y} + \frac{\partial \delta}{\partial d_Y} \right) \right] \\
= \mathcal{J}_{21}^{(\text{SLI})}.$$
(53)

We illustrate the above results for a circular Gaussian PSF.

$$\psi_G(x,y) = \left(\frac{1}{2\pi\sigma^2}\right)^{1/2} \exp\left(-\frac{x^2 + y^2}{4\sigma^2}\right).$$
 (54)

The PSF-dependent quantities appearing in the FI matrix are then given by

$$\delta = \delta_{x}\delta_{y},$$

$$\delta_{x} = \exp\left(-\frac{d_{X}^{2}}{8\sigma^{2}}\right), \quad \delta_{y} = \exp\left(-\frac{d_{Y}^{2}}{8\sigma^{2}}\right),$$

$$\frac{\partial \delta_{x}}{\partial d_{X}} = -\frac{d_{X}}{4\sigma^{2}}\exp\left(-\frac{d_{X}^{2}}{8\sigma^{2}}\right),$$

$$\frac{\partial \delta_{y}}{\partial d_{Y}} = -\frac{d_{Y}}{4\sigma^{2}}\exp\left(-\frac{d_{Y}^{2}}{8\sigma^{2}}\right),$$

$$\frac{\partial \delta}{\partial d_{X}} = \delta_{y}\frac{\partial \delta_{x}}{\partial d_{X}}, \quad \frac{\partial \delta}{\partial d_{Y}} = \delta_{x}\frac{\partial \delta_{y}}{\partial d_{Y}}.$$
(55)

In this example, the FI matrix $\mathcal{J}^{(SLI)}$ has elements

$$\mathcal{J}_{11}^{(\text{SLI})} = \frac{\epsilon_{\text{tot}}}{1 - \delta_x^2} \left(\frac{\partial \delta_x}{\partial d_X}\right)^2,
\mathcal{J}_{22}^{(\text{SLI})} = \frac{\epsilon_{\text{tot}}}{1 - \delta_y^2} \frac{1 + \delta_x}{2} \left(\frac{\partial \delta_y}{\partial d_Y}\right)^2,
\mathcal{J}_{12}^{(\text{SLI})} = \mathcal{J}_{21}^{(\text{SLI})} = 0.$$
(56)

As $d_X, d_Y \rightarrow 0$, the matrix elements approach

$$\mathcal{J}_{11}^{(\mathrm{SLI})} \to \epsilon_{\mathrm{tot}} \Delta k^2 = \mathcal{K}_{33},$$

$$\mathcal{J}_{22}^{(\mathrm{SLI})} \to \epsilon_{\mathrm{tot}} \Delta k^2 = \mathcal{K}_{44},$$
(57)

where $\Delta k^2 = (4\sigma^2)^{-1}$. The FI elements $\mathcal{J}_{11}^{(\mathrm{SLI})}$ and $\mathcal{J}_{22}^{(\mathrm{SLI})}$ of Eq. (56) are plotted as a function of separation parameters d_X and d_Y in Fig. 4. The total source strength $\epsilon_{\mathrm{tot}} = 2 \times 10^{-3}$ photons. The plots are normalized to $\epsilon_{\mathrm{tot}} \Delta k^2$, the values of \mathcal{K}_{33} and \mathcal{K}_{44} . We see that the maximum values of $\mathcal{J}_{11}^{(\mathrm{SLI})}$ and $\mathcal{J}_{22}^{(\mathrm{SLI})}$, attained at $d_X = d_Y = 0$, are equal to the value of the QCR bound obtained in Sec. III for the case of $\epsilon_1 = \epsilon_2$.

Equations (56) indicate, as seen in Figs. 4(a) and 4(b), that the FI $\mathcal{J}_{11}^{(\mathrm{SLI})}$ on d_X remains unchanged despite variation in d_Y , while the FI $\mathcal{J}_{22}^{(\mathrm{SLI})}$ on d_Y depends on values of both d_X and d_Y . This asymmetry is a consequence of our estimating d_X in the first stage of the scheme and d_Y in the second.

A simpler noncascaded version of the scheme may be envisaged in which the input field $\hat{E}(x,y)$ is split using a 50:50 beam splitter, and the two outputs are used to separately estimate d_X and d_Y . Though it treats the separation components symmetrically, such a setup can only approach half of the QCR bound for each component due to the energy splitting. On the other hand, in the cascaded scheme given here, if $d_X \approx 0$, $\delta_x \approx 1$, so that $P(1) \approx 0$, and the single photon, when

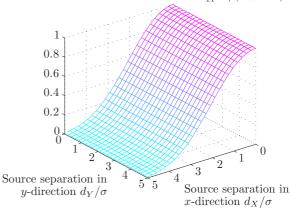
present in the input field, is available with high probability for estimating d_Y in the second stage, allowing the composite setup to approach the QCR bound for sub-Rayleigh separations.

B. Spatial-mode demultiplexing (SPADE)

We now generalize the SPADE scheme of Ref. [14] to the estimation of the vector separation. We assume the circular Gaussian PSF

$$\psi_G(x,y) = \left(\frac{1}{2\pi\sigma^2}\right)^{1/2} \exp\left(-\frac{x^2 + y^2}{4\sigma^2}\right).$$
 (58)

(a) Normalized Fisher information $\mathcal{J}_{11}^{(SLI)}/(\epsilon_{tot} \Delta k^2)$



(b) Normalized Fisher information $\mathcal{J}_{22}^{(\mathrm{SLI})}/(\epsilon_{\mathrm{tot}} \Delta k^2)$

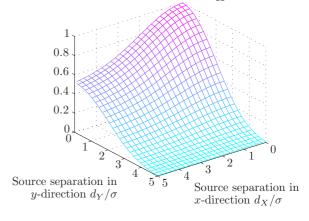


FIG. 4. The (classical) Fisher information matrix $\mathcal{J}^{(\text{SLI})}$ for the SLIVER scheme as a function of the source separation (d_X, d_Y) . (a) Fisher information for x separation $\mathcal{J}_{11}^{(\text{SLI})}$. (b) Fisher information for y separation $\mathcal{J}_{22}^{(\text{SLI})}$. The plots are normalized with respect to the value $\epsilon_{\text{tot}} \Delta k^2$ of \mathcal{K}_{33} and \mathcal{K}_{44} . The quantum bound is attained at $d_X = d_Y = 0$ as illustrated in (a) and (b). The circular Gaussian PSF of Eq. (54) is assumed, with the total source strength $\epsilon_{\text{tot}} = 2 \times 10^{-3}$ photons, and the plots are independent of the half width σ .

In the derivation of the QFI matrix \mathcal{K} in Sec. III, we worked in the orthonormal basis given by Eq. (A9). Now consider the discrete Hermite-Gaussian (HG) basis $\{|\phi_{qr}\rangle; q, r=0,1,\ldots\}$ of wave functions for the one-photon subspace, where

$$|\phi_{qr}\rangle = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \phi_{qr}(x, y) |x, y\rangle, \tag{59}$$

$$\phi_{qr}(x, y) = \left(\frac{1}{2\pi\sigma_X \sigma_Y}\right)^{1/2} \frac{1}{\sqrt{2^{q+r}q!r!}} H_q\left(\frac{x}{\sqrt{2}\sigma_X}\right)$$

$$\times H_r\left(\frac{y}{\sqrt{2}\sigma_Y}\right) \exp\left(-\frac{x^2}{4\sigma_X^2} - \frac{y^2}{4\sigma_Y^2}\right), \tag{60}$$

where H_q and H_r are the Hermite polynomials [36] for $q,r=0,1,\ldots,\sigma_X=\sigma\neq\sigma_Y\equiv s\sigma$. The significance of $s\neq 1$ will appear shortly. Since the Hermite-Gaussian functions are an orthonormal basis for the space of wave functions in the image plane, the projections

$$W_0 = |\text{vac}\rangle\langle\text{vac}|,$$

$$W_1(q,r) = |\phi_{qr}\rangle\langle\phi_{qr}|, \ q,r = 0,1,\dots,$$
(61)

together form a POVM on the vacuum+one-photon subspace of the image-plane field.

The transformation

$$E(x,y) \mapsto E'(x,y) = s^{-1/2}E(x,y/s)$$
 (62)

on the space of image-plane wave functions is unitary, and takes the PSF of Eq. (58) to the elliptical Gaussian

$$\psi'(x,y) = \left(\frac{1}{2\pi\sigma_X\sigma_Y}\right)^{1/2} \exp\left(-\frac{x^2}{4\sigma_X^2} - \frac{y^2}{4\sigma_Y^2}\right)$$
 (63)

$$= \phi_{00}(x, y). \tag{64}$$

It also induces a unitary transformation \hat{U}_s on the one-photon subspace, transforming the state of Eq. (39) to

$$\rho' = \hat{U}_s \rho \, \hat{U}_s^{\dagger},\tag{65}$$

$$= (1 - \epsilon_{\text{tot}})|\text{vac}\rangle\langle\text{vac}| + \epsilon_1|\psi_1'\rangle\langle\psi_1'| + \epsilon_2|\psi_2'\rangle\langle\psi_2'|, \quad (66)$$

where, from Eqs. (37)–(38).

$$\psi_1'(x,y) = \psi'\left(x + \frac{d_X}{2}, y + \frac{s \, d_Y}{2}\right),$$
 (67)

$$\psi_2'(x,y) = \psi'\left(x - \frac{d_X}{2}, y - \frac{s\,d_Y}{2}\right). \tag{68}$$

The POVM (61), if performed on the state ρ' , has the outcome probabilities

$$P_0 \equiv \operatorname{tr}(W_0 \rho') = 1 - \epsilon_{\text{tot}},\tag{69}$$

$$P_1(q,r) \equiv \operatorname{tr}[W_1(q,r)\rho'] \tag{70}$$

$$= \epsilon_1 \left| \langle \phi_{ar} | \psi_1' \rangle \right|^2 + \epsilon_2 \left| \langle \phi_{ar} | \psi_2' \rangle \right|^2. \tag{71}$$

The overlaps in Eq. (71),

$$|\langle \phi_{qr} | \psi_1' \rangle|^2 = \left| \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \phi_{qr}^*(x, y) \right| \times \phi_{00} \left(x + \frac{d_X}{2}, y + \frac{s d_Y}{2} \right) \right|^2, \tag{72}$$

$$|\langle \phi_{qr} | \psi_2' \rangle|^2 = \left| \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \phi_{qr}^*(x, y) \right| \times \phi_{00} \left(x - \frac{d_X}{2}, y - \frac{s d_Y}{2} \right) \right|^2, \tag{73}$$

can be evaluated as in Ref. [14] using properties of Hermite polynomials, viz.,

$$|\langle \phi_{qr} | \psi_1' \rangle|^2 = |\langle \phi_{qr} | \psi_2' \rangle|^2 = \exp(-Q - R) \frac{Q^q R^r}{q! r!}, \quad (74)$$

where

$$Q = \frac{d_{\chi}^2}{16\sigma^2}, \quad R = \frac{d_{\gamma}^2}{16\sigma^2}, \tag{75}$$

so that the probability

$$P_1(q,r) = \epsilon_{\text{tot}} \exp(-Q - R) \frac{Q^q R^r}{q! r!}.$$
 (76)

Using Eq. (15), the FI matrix for the HG-basis measurement on $\eta = (d_X, d_Y)^{\mathsf{T}}$ can be calculated. Its matrix elements are

$$\mathcal{J}_{11}^{(\mathrm{HG})} = \sum_{q,r=0}^{\infty} P_1(q,r) \left[\frac{\partial}{\partial d_X} \ln P_1(q,r) \right]^2 \tag{77}$$

$$= \frac{\epsilon_{\text{tot}}}{Q} \left(\frac{\partial Q}{\partial d_X} \right)^2 = \frac{\epsilon_{\text{tot}}}{4\sigma^2} = \mathcal{K}_{33}, \tag{78}$$

$$\mathcal{J}_{22}^{(\mathrm{HG})} = \sum_{r=0}^{\infty} P_1(q,r) \left[\frac{\partial}{\partial d_Y} \ln P_1(q,r) \right]^2 \tag{79}$$

$$= \frac{\epsilon_{\text{tot}}}{R} \left(\frac{\partial R}{\partial d_{Y}} \right)^{2} = \frac{\epsilon_{\text{tot}}}{4\sigma^{2}} = \mathcal{K}_{44}, \tag{80}$$

$$\mathcal{J}_{12}^{(\text{HG})} = \mathcal{J}_{21}^{(\text{HG})} = 0,$$
 (81)

which exactly equals the QFI matrix given by Eq. (22) if $\epsilon_1 = \epsilon_2$. This proves that the POVM (61) is optimal for a Gaussian PSF.

It remains to show how to implement the POVM (61) corresponding to SPADE using linear optics. The image-plane field in Eq. (2) is first scaled in one direction with a series of mirrors such that the PSF $\psi'(x,y)$ of this augmented system is of the form of Eq. (63). A quadratic-index fiber can support the Hermite-Gaussian mode profiles [37]. A cylindrical fiber will have degenerate propagation constants β_{qr} for modes with the same total order (q + r). Therefore, the optical field is coupled into an elliptical multimode fiber supporting the modes in Eq. (60). If the scaling factor s is chosen carefully, each mode will have a distinct propagation constant β_{ar} along the propagation direction z. The field in the elliptical fiber is then coupled to different single-mode waveguides with matching propagation constants via evanescent coupling, as illustrated in Fig. 5. The phase-matching condition ensures that only one mode from the elliptical fiber is coupled to each waveguide, which are then detected using individual on-off detectors in the far field. In theory, s needs to be an irrational number, but to break the degeneracy for a large enough number of

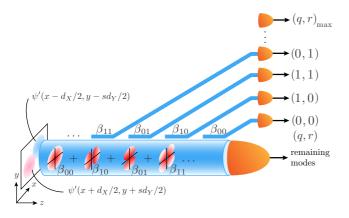


FIG. 5. A schematic drawing of a fiber-optic implementation of SPADE. The image-plane field, scaled in the y direction, is coupled into an elliptical multimode fiber with nondegenerate propagation constants for each of the HG-basis modes $\phi_{qr}(x,y)$. Using evanescent coupling, each mode is coupled to an individual single-mode waveguide of specific propagation constant terminated by an on-off detector. The photon counter at the end of the multimode fiber captures any remaining photon in the higher-order or leaky modes.

modes, s can be taken to be a rational number with a large denominator.

V. MONTE CARLO ANALYSIS OF SLIVER AND SPADE

To demonstrate that the two schemes of Sec. IV perform as predicted by their CR bounds, we implement Monte Carlo simulations of the mean-square error (MSE) for SLIVER and SPADE using maximum-likelihood (ML) estimators [5]. In a sequence of M measurements, the shots in which no photon arrives [which happens with probability $(1-\epsilon_{\rm tot})$ in each shot] are uninformative and can only be discarded. Therefore, it is convenient to condition our analysis on a fixed number L of detected photons. In doing so, instead of considering M copies of the state ρ of Eq. (2), we are effectively considering L copies of the conditional single-photon state,

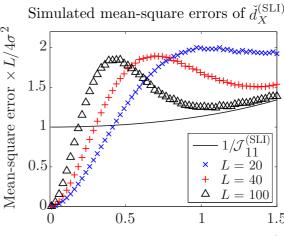
$$\rho' = \frac{1}{2}(|\psi_1\rangle\langle\psi_1| + |\psi_2\rangle\langle\psi_2|),\tag{82}$$

where we have assumed for concreteness that the sources are equally strong. It is readily verified that the (per-shot) conditional QFI and FI matrices for SLIVER and SPADE are obtained by simply dividing the unconditional ones calculated previously by ϵ . In particular, the QFI matrix for the estimation of d_X and d_Y using L copies of ρ' becomes diag($L/4\sigma^2, L/4\sigma^2$) so that the QCR bound for each separation parameter is $4\sigma^2/L$.

In the following, we will adopt this approach for analyzing the performance of SLIVER and SPADE. For all the simulations, the circular Gaussian PSF of Eq. (54) is assumed, and each MSE is computed by averaging over 10⁵ Monte Carlo runs.

A. Monte Carlo analysis of SLIVER

In M trials, consider direct detection of $\hat{E}_1(x,y)$, $E_2(x,y)$, and $E_3(x,y)$ using three on-off bucket detectors as in Fig. 3. Suppose L trials result in photon detections and are postse-



Source separation in x-direction $d_{\rm x}/\sigma$

FIG. 6. Simulated mean-square errors of SLIVER with maximum-likelihood estimator of Eq. (84). The MSE of estimator $\check{d}_X^{(\text{SLI})}$ as a function of the separation in the x direction for L=20,40,100 measurements and $d_Y=0$.

lected, and indexed by $l \in \{1,\ldots,L\}$. The postselected measurement record consists of the bit strings $(g_1^{(1)},g_2^{(1)},\ldots,g_L^{(1)}),$ $(g_1^{(2)},g_2^{(2)},\ldots,g_L^{(2)}),$ and $(g_1^{(3)},g_2^{(3)},\ldots,g_L^{(3)}),$ where $g_l^{(1)},g_l^{(2)},$ and $g_l^{(3)}$ are zero (one) if the corresponding detector did not click (did click) in the lth postselected trial.

The total numbers of clicks observed in the three detectors are, respectively,

$$G^{(1)} = \sum_{l=1}^{L} g_l^{(1)}, \quad G^{(2)} = \sum_{l=1}^{L} g_l^{(2)}, \quad G^{(3)} = \sum_{l=1}^{L} g_l^{(3)}, \quad (83)$$

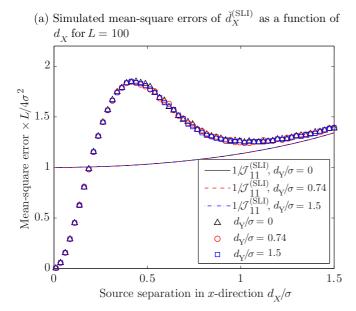
with $L = G^{(1)} + G^{(2)} + G^{(3)}$. For the circular Gaussian PSF, the ML estimators for d_X and d_Y can be shown to be

$$\check{d}_{X}^{(\text{SLI})} = \begin{cases}
2\sigma\sqrt{-2\ln\left(1 - \frac{2G^{(1)}}{L}\right)} & \text{if } \frac{2G^{(1)}}{L} < 1 \\
2\sigma & \text{otherwise,}
\end{cases}$$

$$\check{d}_{Y}^{(\text{SLI})} = \begin{cases}
2\sigma\sqrt{-2\ln\left(1 - \frac{2G^{(2)}}{L - G^{(1)}}\right)} & \text{if } \frac{2G^{(2)}}{L - G^{(1)}} < 1 \\
2\sigma & \text{otherwise.}
\end{cases} (84)$$

The second case for both $\check{d}_X^{(\text{SLI})}$ and $\check{d}_Y^{(\text{SLI})}$ is necessary because the logarithm function $\ln(z)$ in the equations for the estimators is undefined for $z \leq 0$. The estimators are set to an arbitrary value in that event, which happens with vanishing probability as L increases.

Figures 6 and 7 show the simulated MSEs of the ML estimators in Eq. (84). The plotted MSEs are scaled relative to the value of the QCR bound for that L. Figure 6 plots the MSE of $\check{d}_X^{(SLI)}$ as a function of x separation for $d_Y = 0$. The MSE of the estimator $\check{d}_Y^{(SLI)}$ as a function of y separation for $d_X = 0$ is virtually identical to that of Fig. 6 and is not shown. We see that the ML estimator beats the CR bound for small d_X/σ due to the bias of the estimator placing it beyond the purview of the CR bound. This "superefficiency" effect is well known in classical estimation. We refer the reader to Appendix E of Ref. [14] and, in particular, Ref. [38] for extensive discussion



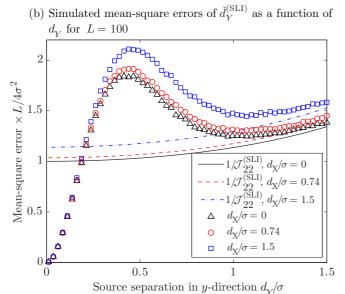


FIG. 7. Simulated mean-square errors of SLIVER with maximum-likelihood estimators of Eq. (84) for different values of d_X and d_Y in L=100 trials. The corresponding Cramér-Rao bounds are included in the plots for comparison. (a) MSE of estimator $\check{d}_X^{(\text{SLI})}$ as a function of the separation in the x direction for $d_Y/\sigma=0.0.74,1.5$. (b) MSE of estimator $\check{d}_Y^{(\text{SLI})}$ as a function of the separation in the y direction for $d_X/\sigma=0.0.74,1.5$.

on this point. Here we just note that the range of d_X values where the estimation is superefficient shrinks with increasing L and limits its practical usefulness.

Figure 7 explores the effect of nonzero values of the separations $d_Y(d_X)$ on the MSE of $\check{d}_X^{(\text{SLI})}(\check{d}_Y^{(\text{SLI})})$ —the number of measurements is fixed at L=100 and the corresponding CR bounds for the relevant separations are shown. Figure 7(a) shows the simulated MSE of estimator $\check{d}_X^{(\text{SLI})}$ as a function of d_X , for $d_Y=0,0.74\sigma$, and 1.5σ . We see that both the estimator and the CR bound show little dependence on the separation d_Y . Figure 7(b) plots the simulated MSE of estimator $\check{d}_Y^{(\text{SLI})}$

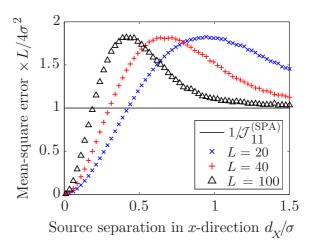


FIG. 8. Simulated mean-square errors of SPADE with maximum-likelihood estimators of Eq. (85). (a) MSE of estimator $\check{d}_X^{(SPA)}$ as a function of the separation in the x direction for L=20,40,100 measurements. The MSE behavior of $\check{d}_Y^{(SPA)}$ as a function of the y separation is similar.

against d_Y for the case of $d_X = 0.0.74\sigma$, and 1.5 σ . As d_X increases, the CR bound increases along with the MSE of the estimator.

B. Monte Carlo analysis of SPADE with maximum-likelihood estimation

Given L photon detections in the SPADE system of Sec. IV B, the postselected measurement record consists of a sequence $\{(q_l, r_l)\}_{l=1}^L$ of index pairs of the two-dimensional HG modes in which the L photons were detected. The ML estimators for d_X and d_Y can be shown to be

$$\check{d}_X^{(\mathrm{SPA})} = 4\sigma\sqrt{\frac{H_X}{L}}, \quad \check{d}_Y^{(\mathrm{SPA})} = 4\sigma\sqrt{\frac{H_Y}{L}},$$
 (85)

where $H_X = \sum_{l=1}^L q_l$ and $H_Y = \sum_{l=1}^L r_l$. Figure 8 displays the results for the MSE of $\check{d}_X^{(\mathrm{SPA})}$. The MSE behavior of $\check{d}_Y^{(\mathrm{SPA})}$ is identical and is not shown. The performance of $\check{d}_X^{(\mathrm{SPA})}(\check{d}_Y^{(\mathrm{SPA})})$ is independent of the value of $d_Y(d_X)$. These behaviors are expected from Eq. (76)—the joint probability of q and r is a product of their marginal distributions that, respectively, depend only on d_X and d_Y in identical fashion. The ML estimators beat the CR bounds in the estimation of d_X and d_Y for small separations. The errors remain less than twice the CR bounds for any separations.

VI. DISCUSSION AND OUTLOOK

In this paper, we have calculated the QCR bound for locating two weak incoherent optical point sources on a two-dimensional plane using an imaging system with any given inversion-symmetric point-spread function. The key result is that in stark contrast to spatially resolved direct imaging [4,14], the bounds on the MSE of estimating the *x* and *y* separations are independent of the vector separation between the two sources. Strictly speaking, a large enough separation can take us outside the scalar-field paraxial approximation

assumed here, but that approximation is excellent for most practical applications in microscopy and telescopy.

We have also proposed and analyzed two measurement schemes—the extended SLIVER and SPADE schemes—for simultaneously estimating the components of the separation, whose classical CR bounds approach the quantum bounds for sub-Rayleigh separations (SLIVER) or all separations if the PSF is Gaussian (SPADE). Monte Carlo simulations show that the two schemes have MSEs no larger than twice that predicted by the quantum limits for values of source separation from zero to beyond the PSF width.

The extended SLIVER scheme given here does not employ an image-inversion device (see, e.g., Refs. [39,40], in which the general properties of the device were studied, and Ref. [17] for an implementation in the context of two-source resolution), which was required in the scheme of Ref. [16] tailored to directly estimate the magnitude $d = \sqrt{d_X^2 + d_Y^2}$ of the separation. Thus, each interferometer stage in the current scheme may be technically simpler to implement than that of Ref. [16], and especially if only one component of the separation is of interest. However, the original scheme is likely to be superior for estimation of $d = \sqrt{d_X^2 + d_Y^2}$, as suggested by the dependence of the MSE of $\check{d}_Y^{(\text{SLI})}$ on d_X in the simulations in Sec. V.

Our analysis here can be extended in various directions. By adopting the Gaussian-state source model of Ref. [21], our quantum Fisher information calculations can, in principle, be extended to sources of arbitrary strength. The study of two-source transverse localization can also be generalized to sources emitting light in more general quantum states, as in Ref. [22]. In principle, it can also be extended to multiple sources, although finding near-optimal measurement schemes is likely to be challenging. The performance of the SPADE and SLIVER schemes can also be analyzed in the thermal-state model in the spirit of Ref. [16]. Even with the same source model as here, the performance of SPADE employing only a finite number of HG modes and extensions of the SLIVER scheme using pixelated detectors (cf. the fin-SPADE and pix-SLIVER schemes of [21]) can be explored, as well as generalizations enabling full transverse localization of the sources. This problem will be explored in the future.

In both measurement schemes, we have assumed that the centroid position is known. If that knowledge is unavailable, a portion of the light can be used for image-plane photon counting to determine the centroid position before performing either of the schemes, as detailed in Ref. [14]. To account for the residual error in estimating the centroid, it is important to study the performance of SLIVER and SPADE if the centroid is not aligned to the optical axis. Among the other practical questions to be explored are the effects of nonunity coupling efficiency in SPADE, and unequal detection efficiencies of the detectors.

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APPENDIX A: QUANTUM FISHER INFORMATION MATRIX

To evaluate the QFI matrix, we first need to diagonalize ρ including enough eigenvectors to span the combined support of ρ and the $\{\partial\rho/\partial\theta_{\mu}\}$. The partial derivatives of ρ with respect to the object-plane source coordinates X_{μ} and Y_{μ} are

$$\begin{split} \frac{\partial \rho}{\partial X_{\mu}} &= \frac{\partial D_{1}}{\partial X_{\mu}} |e_{1}\rangle\langle e_{1}| + \frac{\partial D_{2}}{\partial X_{\mu}} |e_{2}\rangle\langle e_{2}| \\ &+ \left(D_{1} \frac{\partial |e_{1}\rangle}{\partial X_{\mu}} \langle e_{1}| + D_{2} \frac{\partial |e_{2}\rangle}{\partial X_{\mu}} \langle e_{2}| + \text{H.c.}\right), \quad \text{(A1)} \\ \frac{\partial \rho}{\partial Y_{\mu}} &= \frac{\partial D_{1}}{\partial Y_{\mu}} |e_{1}\rangle\langle e_{1}| + \frac{\partial D_{2}}{\partial Y_{\mu}} |e_{2}\rangle\langle e_{2}| \\ &+ \left(D_{1} \frac{\partial |e_{1}\rangle}{\partial Y_{\mu}} \langle e_{1}| + D_{2} \frac{\partial |e_{2}\rangle}{\partial Y_{\mu}} \langle e_{2}| + \text{H.c.}\right), \quad \text{(A2)} \end{split}$$

where H.c. denotes the Hermitian conjugate. For any (possibly complex-valued) $\psi(x, y)$ symmetric about the origin, viz.,

$$\psi(x, y) = \psi(-x, -y), \tag{A3}$$

here we show that the overlap δ given by Eq. (5) is real valued. The complex conjugate of δ is given by

$$\delta^* = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \psi(x - X_1, y - Y_1) \psi^*(x - X_2, y - Y_2). \tag{A4}$$

By applying the transformations

$$x \mapsto \frac{\bar{X}}{2} - x, \quad y \mapsto \frac{\bar{Y}}{2} - y,$$
 (A5)

and flipping the limits of both integrations, we have

$$\delta^* = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \psi\left(-x + \frac{d_X}{2}, -y + \frac{d_Y}{2}\right)$$
$$\times \psi^*\left(-x - \frac{d_X}{2}, -y - \frac{d_Y}{2}\right), \tag{A6}$$

where \bar{X}, \bar{Y}, d_X , and d_Y are defined in Eqs. (8) and (9). Using the symmetricity of $\psi(x, y)$,

$$\delta^* = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \psi \left(x - \frac{d_X}{2}, y - \frac{d_Y}{2} \right)$$

$$\times \psi^* \left(x + \frac{d_X}{2}, y + \frac{d_Y}{2} \right)$$

$$= \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \, \psi(x - X_2, y - Y_2) \psi^*(x - X_1, y - Y_1)$$

$$= \delta,$$
(A7)

where we apply the transformations

$$x \mapsto x - \frac{\bar{X}}{2}, \quad y \mapsto y - \frac{\bar{Y}}{2},$$
 (A8)

in the second equality. Hence, δ is real valued.

After some algebra, it can be shown that a possible set of eigenvectors of ρ is

$$|e_{0}\rangle = |\operatorname{vac}\rangle, \quad |e_{1}\rangle = \frac{1}{\sqrt{2(1-\delta)}}(|\psi_{1}\rangle - |\psi_{2}\rangle), \quad |e_{2}\rangle = \frac{1}{\sqrt{2(1+\delta)}}(|\psi_{1}\rangle + |\psi_{2}\rangle),$$

$$|e_{3}\rangle = \frac{1}{c_{3}} \left[\Delta k_{X}(|\psi_{1X}\rangle + |\psi_{2X}\rangle) + r_{+} \Delta k_{Y}(|\psi_{1Y}\rangle + |\psi_{2Y}\rangle) - \frac{2(\gamma_{X} + r_{+}\gamma_{Y})}{\sqrt{2(1-\delta)}} |e_{1}\rangle \right],$$

$$|e_{4}\rangle = \frac{1}{c_{4}} \left[\Delta k_{X}(|\psi_{1X}\rangle + |\psi_{2X}\rangle) - r_{+} \Delta k_{Y}(|\psi_{1Y}\rangle + |\psi_{2Y}\rangle) - \frac{2(\gamma_{X} - r_{+}\gamma_{Y})}{\sqrt{2(1-\delta)}} |e_{1}\rangle \right],$$

$$|e_{5}\rangle = \frac{1}{c_{5}} \left[\Delta k_{X}(|\psi_{1X}\rangle - |\psi_{2X}\rangle) + r_{-} \Delta k_{Y}(|\psi_{1Y}\rangle - |\psi_{2Y}\rangle) + \frac{2(\gamma_{X} + r_{-}\gamma_{Y})}{\sqrt{2(1+\delta)}} |e_{2}\rangle \right],$$

$$|e_{6}\rangle = \frac{1}{c_{6}} \left[\Delta k_{X}(|\psi_{1X}\rangle - |\psi_{2X}\rangle) - r_{-} \Delta k_{Y}(|\psi_{1Y}\rangle - |\psi_{2Y}\rangle) + \frac{2(\gamma_{X} - r_{-}\gamma_{Y})}{\sqrt{2(1+\delta)}} |e_{2}\rangle \right],$$
(A9)

where δ is given by Eq. (5), $\Delta k_X, \Delta k_Y, \gamma_X, \gamma_Y$ are defined in Eq. (19),

$$\begin{split} |\psi_{1X}\rangle &\equiv \frac{1}{\Delta k_X} \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{\partial \psi(x-X_1,y-Y_1)}{\partial X_1} |x,y\rangle, \\ |\psi_{2X}\rangle &\equiv \frac{1}{\Delta k_X} \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{\partial \psi(x-X_2,y-Y_2)}{\partial X_2} |x,y\rangle, \\ |\psi_{1Y}\rangle &\equiv \frac{1}{\Delta k_Y} \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{\partial \psi(x-X_1,y-Y_1)}{\partial Y_1} |x,y\rangle, \\ |\psi_{2Y}\rangle &\equiv \frac{1}{\Delta k_Y} \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{\partial \psi(x-X_2,y-Y_2)}{\partial Y_2} |x,y\rangle, \\ c_3 &\equiv 2\sqrt{\Delta k_X^2 + b_X^2 - \frac{\gamma_X^2}{1-\delta}} + |r_+| \left| a + a_s - \frac{\gamma_X \gamma_Y}{1-\delta} \right|, \\ c_4 &\equiv 2\sqrt{\Delta k_X^2 + b_X^2 - \frac{\gamma_X^2}{1-\delta}} - |r_+| \left| a + a_s - \frac{\gamma_X \gamma_Y}{1-\delta} \right|, \\ c_5 &\equiv 2\sqrt{\Delta k_X^2 - b_X^2 - \frac{\gamma_X^2}{1+\delta}} + |r_-| \left| a - a_s - \frac{\gamma_X \gamma_Y}{1+\delta} \right|, \\ c_6 &\equiv 2\sqrt{\Delta k_X^2 - b_X^2 - \frac{\gamma_X^2}{1+\delta}} - |r_-| \left| a - a_s - \frac{\gamma_X \gamma_Y}{1+\delta} \right|, \\ r_{\pm} &\equiv \left[\frac{\Delta k_X^2 \pm b_X^2 - \gamma_X^2/(1\mp\delta)}{\Delta k_Y^2 + b_Y^2 - \gamma_Y^2/(1\mp\delta)} \right]^{1/2} \\ &\times \exp\left[-i \arg\left(a \pm a_s - \frac{\gamma_X \gamma_Y}{1+\delta} \right) \right], \\ a &\equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{\partial \psi^*(x,y)}{\partial x} \frac{\partial \psi(x,y)}{\partial y}, \\ a_s &\equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \frac{\partial \psi^*(x,y)}{\partial x} \frac{\partial \psi(x-d_X,y-d_Y)}{\partial y}, \\ b_X^2 &\equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \left[\frac{\partial \psi^*(x-X_1,y-Y_1)}{\partial X_1} \right], \\ \times \frac{\partial \psi(x-X_2,y-Y_2)}{\partial Y_2} \right], \end{split}$$

$$b_Y^2 \equiv \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \left[\frac{\partial \psi^*(x - X_1, y - Y_1)}{\partial Y_1} \right] \times \frac{\partial \psi(x - X_2, y - Y_2)}{\partial Y_2}, \tag{A10}$$

and the eigenvalues of ρ (D_n corresponding to $|e_n\rangle$) are

$$D_0 = 1 - \epsilon, \quad D_1 = \frac{\epsilon}{2}(1 - \delta), \quad D_2 = \frac{\epsilon}{2}(1 + \delta),$$

 $D_3 = D_4 = D_5 = D_6 = 0.$ (A11)

The SLDs with respect to the derivative in Eqs. (A1) and (A2) can be found using Eq. (17),

$$\mathcal{L}_{\mu}^{(X)} = \sum_{\substack{m,n \\ D_m + D_n \neq 0}} \frac{2}{D_m + D_n} \langle e_m | \frac{\partial \rho}{\partial X_{\mu}} | e_n \rangle | e_m \rangle \langle e_n |,$$

$$\mathcal{L}_{\mu}^{(Y)} = \sum_{\substack{m,n \\ D_m + D_n \neq 0}} \frac{2}{D_m + D_n} \langle e_m | \frac{\partial \rho}{\partial Y_{\mu}} | e_n \rangle | e_m \rangle \langle e_n |. \quad (A12)$$

Transforming to the centroid and separation parameters θ of Eq. (7) gives the SLDs

$$\mathcal{L}_{1} = \mathcal{L}_{1}^{(X)} + \mathcal{L}_{2}^{(X)}, \quad \mathcal{L}_{2} = \mathcal{L}_{1}^{(Y)} + \mathcal{L}_{2}^{(Y)},$$

$$\mathcal{L}_{3} = \frac{\mathcal{L}_{2}^{(X)} - \mathcal{L}_{1}^{(X)}}{2}, \quad \mathcal{L}_{4} = \frac{\mathcal{L}_{2}^{(Y)} - \mathcal{L}_{1}^{(Y)}}{2}. \tag{A13}$$

We can now evaluate the quantum Fisher information using Eq. (16) to finally obtain Eq. (18).

APPENDIX B: THE STATISTICS OF SLIVER

In this appendix, we compute the probabilities [Eq. (47)]

$$P(r) = \text{tr}(\rho \hat{N}_r) \ (r = 1, 2, 3),$$
 (B1)

$$= \sum_{s=1,2} \epsilon_s \langle \Psi_s | \hat{N}_r | \Psi_s \rangle, \tag{B2}$$

of the three possible cases of detecting one photon in the SLIVER measurement. Here, the states

$$|\Psi_s\rangle = |\psi_s\rangle|0\rangle_1|0\rangle_2, \quad s = 1,2, \tag{B3}$$

as the single-photon source states augmented with vacuum states in the extra beam-splitter input modes $\hat{V}_1(x,y)$ and $\hat{V}_2(x,y)$. From Eq. (45) and Eqs. (41)–(44), knowledge of the second moments

$$\langle \Psi_{\rm s} | \hat{E}^{\dagger}(x, y) \hat{E}(x', y') | \Psi_{\rm s} \rangle,$$
 (B4)

$$\langle \Psi_s | \hat{E}^{\dagger}(x, y) \hat{V}_1(x', y') | \Psi_s \rangle,$$
 (B5)

$$\langle \Psi_s | \hat{E}^{\dagger}(x, y) \hat{V}_2(x', y') | \Psi_s \rangle,$$
 (B6)

$$\langle \Psi_s | \hat{V}_1^{\dagger}(x, y) \hat{V}_1(x', y') | \Psi_s \rangle,$$
 (B7)

$$\langle \Psi_s | \hat{V}_1^{\dagger}(x, y) \hat{V}_2(x', y') | \Psi_s \rangle,$$
 (B8)

$$\langle \Psi_s | \hat{V}_2^{\dagger}(x, y) \hat{V}_2(x', y') | \Psi_s \rangle,$$
 (B9)

for arbitrary (x,y) and (x',y') and for s=1,2, suffices to calculate Eq. (B1). Since $\hat{V}_1(x,y)$ and $\hat{V}_2(x,y)$ are in vacuum, the only nonzero second moment is Eq. (B4). To calculate $\langle \Psi_s | \hat{E}^\dagger(x,y) \hat{E}(x',y') | \Psi_s \rangle$, expand the image-plane field in terms of a complete orthonormal set $\{\varphi_q(x,y)\}_{q=0}^\infty$ with

associated annihilation operators $\{\hat{a}_q\}_{q=0}^{\infty}$ such that $\varphi_0(x,y) = \psi_1(x,y)$:

$$\hat{E}(x,y) = \hat{a}_0 \psi_1(x,y) + \sum_{q=1}^{\infty} \hat{a}_q \varphi_q(x,y).$$
 (B10)

Then, by definition of the single-photon state (3), the mode \hat{a}_0 is in a single-photon state while $\{\hat{a}_q\}_{q=1}^{\infty}$ are all in vacuum. It follows that

$$\langle \Psi_{1} | \hat{E}^{\dagger}(x, y) \hat{E}(x', y') | \Psi_{1} \rangle = \langle 1 | \hat{a}_{0}^{\dagger} \hat{a}_{0} | 1 \rangle \ \psi_{1}^{*}(x, y) \psi_{1}(x', y')$$
(B11)

$$= \psi_1^*(x, y)\psi_1(x', y').$$
 (B12)

Using a similar mode expansion for s = 2, we have, generally,

$$\langle \Psi_s | \hat{E}^{\dagger}(x, y) \hat{E}(x', y') | \Psi_s \rangle = \psi_s^*(x, y) \psi_s(x', y'), \quad s = 1, 2.$$
(B13)

Using this along with Eqs. (41)–(44) to evaluate Eq. (B1) results in Eqs. (49) of Sec. IV A.

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