Self-Powered Dual-Mode Amenity Sensor Based on the Water–Air Triboelectric Nanogenerator

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ABSTRACT: A water–air triboelectric nanogenerator (WATENG) is presented for CO2 sensing application. During the operation of WATENG, two independent charge transfers can be used to characterize the effect of force and humidity, respectively. Thus, the structure of WATENG provides a capability to eliminate these two major interferences in a triboelectric self-powered sensor. With the aid of the polyethylenimine (PEI) coating, WATENG can be used for CO2 sensing in both static and dynamic conditions. In static condition with a stable CO2 concentration, the CO2 sensing is characterized with respect to different relative humidity, and the sensing range can be up to 6000 ppm. In dynamic CO2 sensing of a pulse gas spray, due to the fast recovery of PEI surface reaction, the sensing range of dynamic situation can be broadened to 30,000 ppm. The self-powered and portable feature of WATENG is preferable as a self-powered amenity sensor for the construction of internet of the things (IoT) sensor networks in the future.

KEYWORDS: portable, CO2 sensing, humidity calibration, force free, charge-based characterization

Modern smart buildings provide amenities to users with the aid of advanced demand-controlled heating ventilation air conditioning (HVAC) systems,1 where it requires advanced sensor networks to control the parameters such as temperature, humidity, and CO2 concentration. By leveraging the MEMS technology, a few amenity sensors of minimized dimension are developed to fit requirements of the sensor networks.2−7 However, one of the essential issues that cannot be bypassed is the power consumption of present commercial amenity sensors. Taking the CO2 monitor, the main indicator of indoor air quality (IAQ), as an example, the information on air flow at different locations in a large indoor space (such as office floor, ballroom, auditorium, and lobby, etc.) needs to be collected in a real-time manner such that the individually controlled dampers in this large indoor space can separately regulate the distribution of air-flow. For the construction of large-scale sensor networks and internet of the things (IoT) sensor networks used in smart buildings in the future, the sensor nodes in the system need to have the capability of operating independently, sustainably, and maintenance-free. Otherwise, because massive sensor nodes are distributed within the entire area, periodic replacement of batteries in sensor nodes is a labor intensive task and will create a significant amount of waste materials from batteries, as they are environmentally unfriendly and potentially hazardous to human health.8 Therefore, self-powered sensor nodes are crucial for enabling a sensor network without using batteries.8,9

In the past decade, triboelectric nanogenerators (TENGs) show the great potential for applications in mechanical energy harvesters and self-powered sensors.11−19 The versatile nature of TENGs enables the capability of sensing all parameters that are relevant to the factors affecting the performance such as force, frequency, and surface charge density. Recently, various types of triboelectric-based sensors have been investigated such as the pressure sensor,20−25 vibration sensor,26−29 motion

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sensor,30−32 liquid sensor,33,34 and chemical/environmental sensor.35−40 However, the versatile nature of the triboelectric sensor also means that more interference will be introduced with the application of sensing a specific parameter. One critical issue reported in usage of the triboelectric sensor is the interference of humidity. Water vapor in air will affect the generation of electrostatic charge, which is the key factor for contact electrification in triboelectric sensors. The previous study confirms that the humidity fluctuation within a small range can induce a large variation of the triboelectric output.41−45 Therefore, a proper calibration or even elimination of humidity effect is necessary to enhance the sensing accuracy of triboelectric-based sensors.

So far, several kinds of triboelectric chemical sensors have been investigated, such as Hg2+ ion sensing35 and catechin sensing,36 however, gas sensing is still a rarely touched field. A preliminary study reports a stacked corrugated-core sandwich-structured TENG for H2 sensing.40 Although the detailed sensing mechanism still remains unknown and the result shows no sensing selectivity to other gas species, it reveals a gas sensing feasibility by triboelectric mechanism. In this study, a polyethilenimine (PEI) layer was used as the CO2 selective sensing material incorporated in TENG gas sensors. Hence, it becomes possible to develop a TENG gas sensor with high sensitivity by having a special functional coating on top of the triboelectric layer, where only a specific gas molecule can alter the surface property of that functional material. Compared with current CO2 sensors,44−48 PEI can avoid the issues of cross-sensitivity, long response time, poor reversibility, and poor sensitivity which are mainly introduced by imperfect sensing material properties.46−48 In the previous study, only the infrared investigation of CO2 bulk absorption in the PEI layer was conducted for measuring the CO2 concentration.44−45 By investigating the change of the surface charge of PEI with CO2 absorption, a simple triboelectrification process can replace the desktop FTIR equipment for CO2 detection.

Here we propose a water−air triboelectric nanogenerator (WATENG) as a portable CO2 sensing device. Meanwhile, the effect of humidity for CO2 sensing using PEI is calibrated. This is a preliminary study that investigates how water molecules affect surface charge density so as to enable self-generated triboelectric-based gas detection from the output charge.

RESULTS AND DISCUSSION

WATENG Mechanism Analysis and Output Characterization. Figure 1a shows a device configuration in the WATENG for CO2 detection. This WATENG is comprised of a top air layer and a bottom wetted sponge layer that is separated via a suspended PDMS thin film at the center. The contact electrification between the top electrode and the upper surface of PDMS has a constant contact area with a mutative humidity of the ambient environment. For the contact electrification between the lower surface of PDMS and wetted sponge, this contact area is a function of applied force where the humidity is kept at a maximum and stable. Thus, during the operation, there will be two independent charge-transfer mechanisms: One is not affected by force, and another is not affected by humidity. Hence, humidity and force can be characterized independently. In a previous investigation of triboelectric-based sensors, a force control system is required for a stable operation force to induce contact and separation.30−40 This force control system makes the entire sensing system not portable. Therefore, TENGs can generate a stable output with varied force or even directly measure the force, which is essential for developing portable self-powered chemical sensors operated manually.

The CO2 sensing concept is shown in Figure 1b. The PEI coating on the top electrode can absorb CO2 and further change the electronegativity of its surface. Hence, the change of the triboelectric output can be used to measure the CO2 concentration. For most cases, the change in CO2 concentration is usually accompanied by a change of relative humidity (RH), for example, during exhalation. The effect of gaseous water in CO2 sensing is characterized in this study.

The detailed WATENG structure is shown in Figure 1a. The entire device includes four layers. The top and bottom ITO/PET electrodes act as the electrode pair of the device. The PEI layer, which is a type of macromolecule for CO2 adsorbents, was dip-coated onto the top ITO/PET electrode. A sponge is located at the center of the bottom ITO/PET electrode. During the operation, the sponge is wetted with water, then the water can be squeezed out. This function plays an important role for force sensing and output enhancement. The PDMS thin film, which is located between the sponge and the top ITO/PET electrode, is fixed and stretched by a frame to provide contact electrification between the two top electrodes and triboelectric charge due to water being squeezed out from the sponge. A
detailed fabrication process and optical and SEM images of the WATENG can be found in Supplementary S1.

**Working Mechanism of WATENG with PEI for Gas Sensing.** The working mechanism is illustrated in Figure 2a. The entire operation will induce a charge flow cycle, as shown in Figure 2c. After the first cycle of operation, the suspended PDMS thin film obtains negative electrostatic charges on both the upper surface, which is \( q_1 \), and the lower surface, which is \( q_2 \), as shown in Figure 2a-i. In this step, the top ITO/PET electrode is separated from the PDMS thin film. Then, the ITO/PET electrode is pressed to produce a contact with the PDMS thin film, as shown in Figure 2a-ii. Due to the contact between ITO and PDMS surface, the negative electrostatic charges on both sides of the PDMS thin film will be balanced by the positive charge on the ITO/PET electrode, inducing a charge flow, which is \( q_1 + q_2 \), from the bottom ITO/PET electrode to the top ITO/PET electrode, which is indicated as \( I_1 \) in Figure 2c. Then, we further press the top electrode to deform the suspended PDMS thin film and compress the wetted sponge, as shown in Figure 2a-iii. In this step, the water within the wetted sponge will be squeezed out from the sponge and contact the lower surface of the PDMS thin film. Hence, the negative electrostatic charge on the lower surface of the PDMS thin film, \( q_2 \), which is initially balanced by the positive charge on the top electrode, will be coupled by positive ions in water, which will form a so-called electric double layer. During this step, a charge flow from the top electrode to the bottom electrode will be induced, indicated as \( I_2 \) in Figure 2c. Then, the top electrode is lifted up to make the sponge absorb all of the water back, as shown in Figure 2a-iv. Again, without the electric double layer being formed by the contact between water and the lower surface of PDMS, the negative electrostatic charge on the lower surface of the PDMS thin film will be balanced by the positive charge on the top electrode, which induces a charge flow \( q_2 \) from the bottom electrode to the top electrode. Due to the sticky surface of PDMS, PDMS can be lifted up together with the top electrode to a certain height before the complete separation occurs, as shown in Figure 2a-iv. In this step, the distance between the bottom electrode and PDMS thin film is increasing, which will further lower the electrostatic induction between them. Thus, a very small charge flow, \( q_3 \) from the bottom electrode to the top electrode will occur. During the entire lifting up process, a charge flow, indicated as \( I_3 \), which is comprised of \( q_2 \) and \( q_3 \) in Figure 2c, will occur. If the top electrode is further lifted up, PDMS will completely separate from the top electrode, making the entire device recover to the initial status as shown in Figure 2a-iv. The negative electrostatic charge on both sides of the PDMS thin film will be balanced by the entire environment, and a charge flow of \( I_4 \) which is comprised of \( q_1 \), \( q_2 \), and \( q_3 \) from the top electrode to the bottom electrode will occur, as indicated in Figure 2c.

As explained in the working mechanism, the charge transfer in the entire cycle is determined by the negative electrostatic charge on both sides of the PDMS thin film. The total negative electrostatic charge should be the sum of \( q_1 \), \( q_2 \), and \( q_3 \). Among them, \( q_3 \) refers to the change of the electrostatic induction between the top and bottom electrodes during the lifting up process and is negligible because it is much lower than \( q_1 \) and \( q_2 \).
for most cases. Then, $q_1$ and $q_2$ can be considered as the charges on the upper and lower surfaces of the PDMS thin film, respectively.

**Analysis of Output Affected by Force and Relative Humidity.** The RH and force are the two major factors that make the performance of TENGs unstable. Although it has been reported that water molecules can help stabilize the charge generated by contact electrification, a higher RH will deteriorate the performance of TENGs in terms of charge and voltage characteristics. Force will affect the contact area, which directly determines the amount of electrostatic charge that participates in electrostatic induction. Here, we made a detailed study of how $q_1$ and $q_2$ are affected by RH and force.

Figure 2b shows the total charge transferred, which is the sum of $q_1$ and $q_2$ at a different force, RH, and water volume inside the sponge. The higher volume of water inside the sponge will have a larger contact area between water and PDMS when the sponge is squeezed with the same force. When the force is lower than 1.5 N, the total charge for water volume of 1 and 1.75 mL is the same. This means that almost no water was squeezed out from the sponge. When the force is higher than 1.5 N, the charge curve of 1.75 mL is always higher than that of 1 mL because more water was squeezed out of the sponge to induce a larger contact area between water and PDMS. The characterization of $q_1$ and $q_2$ which constitute the total charge in Figure 2b, is shown in Figure 2c,d, respectively. As shown in Figure 2d, $q_1$ significantly increases when RH decreases. This nonlinear change indicates that the charge output will logarithmically increase with a decrease of RH, which is consistent with the result reported in ref 43, and $q_1$ remains constant by changing the force. Because the PDMS thin film was suspended by a frame, the top electrode will always fully contact the PDMS upper surface even with a very small pressing force, which results in a constant contact area. In
addition, this constant $q_1$ with different force also confirms that $q_1$ represents the charge on the upper surface of the PDMS thin film. Figure 2e shows $q_2$ as a function of changing RH and force, and $q_2$ increases with increasing force and remains...
constant at different RH. A larger force leads to more water being squeezed out from the sponge and increases the contact area between water and PDMS. Thus, more negative electrostatic charge can be balanced by the electric double layer, which induces a higher $q_1$. However, RH has little effect on $q_2$. This is because RH of the contact surface between PDMS and water is already at maximum due to the involvement of water. This maximum RH will not be further affected by the change of RH in the ambient environment. A group of charge curves of the samples with 5 N of applied force with different RH is shown in Figure 2f. Although the total transferred charge increases with a decrease of RH, $q_2$ is the same.

In summary, two main components of the total transferred charge of WATENG, which are $q_1$ and $q_2$, are solely controlled by RH and force, respectively. Thus, based on the calibration, WATENG can be simultaneously used as a sensor for RH and force.

**Characterization of Output Enhancement.** Based on the explanation above, the electrostatic charge on both the upper and lower surfaces of the PDMS thin film is used for generating the output. Apparently, compared with conventional TENGs, in which only the upper surface of the dielectric layer is used for generating output, the structure of the WATENG can generate more electrostatic charge, hence enhancing the output. Here we have a characterization of the output of five different structures of TENGs, including conventional TENGs and WATENG. Considering that PTFE is a more popular material as the dielectric to be used in TENGs for higher energy output,32,49,50 we used PTFE thin film instead of PDMS thin film for all the five cases for the comparison of the output.

The structures and the output voltage of the five cases are shown in Figure 3a. Case 1 shows a conventional structure of the TENGs. The PTFE thin film was directly attached onto the bottom electrode. The output voltage was generated by the contact and separation of the top electrode and the upper surface of the PTFE thin film. Cases 2 and 3 show a suspended PTFE thin film structure without a sponge beneath. The suspended PTFE thin film will not contact the bottom electrode during the pressing in case 2 and will have contact with the bottom electrode in case 3. Cases 4 and 5 are the same structure as shown in Figure 2 but with a dry sponge and a wetted sponge, respectively.

The output voltage of case 1, which is 400 V, is lower than that of case 5, which is 530 V, as shown in Figure 3b. This confirms that our structure can achieve a higher output than conventional TENGs structure.

By hard pressing in cases 2 and 3, the suspended thin film contacts the bottom electrode to generate a higher output. This is due to that the lower surface of the suspended thin film contacts the bottom electrode, and the negative electrostatic charge is generated on the lower surface of the thin film. Thus, there will be a similar double side charge coupling during the pressing, hence enhancing the output. However, because of the air gap, which leads to a large inner impedance, the output voltage is much lower compared to case 5.

For case 4, since the sponge is dry, no water can be squeezed out of the sponge. The electrification between the PTFE and sponge cannot be as efficient as either between the water and PTFE or between the PTFE and ITO. Although there is negative charge generated upon the lower surface of the PTFE thin film, the output voltage is still lower than cases 3 and 5.

We also characterize the output power and inner impedance for cases 1 and 5, as shown in Figure 3c, since these two give the best performance. As can be seen, the output voltage of case 5 was always higher than case 1. The maximum output power for case 5 is 15.2 mW at 3.47 MΩ, while for case 1, it is 9.55 mW at 9.4 MΩ. The WATENG structure of case 5 can achieve not only higher optimum output power but also a lower matched load resistance.

In summary, the developed WATENG structure with a suspended thin film and wetted sponge can enhance the performance compared with a conventional TENG structure. In this research, we did not optimize the material of the suspended thin film. Actually a lot of techniques, including the surface treatment, surface coating, and better material selection, are investigated to enhance the output. The suspended thin-film structure is compatible with all these material optimizations for a better performance.

**Static CO₂ Sensing at Different RH.** To demonstrate the application of WATENG as a CO₂ sensor, a layer of polyethylenimine (PEI) was dip-coated onto the ITO/PET electrode. The PEI is the most commonly used macromolecule for CO₂ adsorbents because of its high amine content in the polymer backbone; primary, secondary, and tertiary amines make up 33% of the total weight.51 With absorption of CO₂ within PEI, the formation of a carbamate layer, which is a CO₂–PEI complexation,52 will change the electronegativity of the PEI surface, which affects the output of WATENG.

Currently, how the CO₂–PEI complexation affects the WATENG performance remains unknown. A static characterization was conducted to provide detailed investigation. The ITO/PET electrode coated with PEI was kept in a sealed chamber with a controlled CO₂ concentration and RH for 30 min to ensure that the NH–CO₂ production reaction was stable. The test setup can be found in Supplementary S2. Then, we removed the electrode and assembled it on the WATENG for testing, as shown in Figure 4a. Here, we also investigated how $q_1$ and $q_2$ were affected. A group of charge curves at ambient environment with different forces is shown in Figure 4c, where $q_1$ increases with force, while $q_2$ remains constant. In addition, for the samples that are kept at the same CO₂ concentration, 6250 ppm, with different RH, $q_1$ decreases with an increase of RH, while $q_2$ remains constant. The results are consistent with a previous working mechanism analysis. Since the PEI coating only affects the electrification between the upper PDMS layer and the top electrode, which is represented by $q_1$, only the change of $q_2$ was used to characterize the influence of CO₂ absorption in PEI.

In Figure 4b, $q_1$ is shown under different RH and CO₂ concentrations. For the RH of 40%, which can generate the highest charge transfer, $q_1$ increases with CO₂ concentration and peaks at 6250 ppm. Then, $q_1$ drops from 3.2 nC to 1.85 nC when the CO₂ concentration increases from 6250 to 12750 ppm.

The curves of higher RH levels also show the same trend. This nonmonotonous change indicates that there are more than one factor that affect surface electronegativity of the PEI surface. Indeed, the absorption of CO₂ on PEI gives rise to several absorbed species:53-55 carbamate-ammonium ion pairs, zwitterions, and carbamic acid, as shown below, where $R_1R_2NH$ can be a primary or a secondary amine molecule:

$$R_1R_2NH + CO_2 \rightarrow R_1R_2NH^+COO^- \text{ Zwitterion}$$ (1)
Figure 5. Dynamic CO$_2$ concentration characterization. (a) Testing procedure. (b) The value of $\Delta q_1$ with a gas spray of different CO$_2$ concentrations at an ambient environment. (c) Charge-transfer curve showing the change of $q_1$ when the PEI surface was blown with a CO$_2$ spray. (d) The value of $q_1$ of each pulse in (c). (e) IR spectra of PEI coated on a molybdenum substrate: black line (overlapped with the blue line) is the initial IR spectrum when the chamber is filled with ambient air; the red line is the IR spectrum when the chamber is filled with 2000 ppm of CO$_2$ gas concentration; and the blue line is the IR spectrum when the chamber is flushed again with ambient air. (f) The normalized reflectivity at 2.97 $\mu$m for the entire experiment shown in (e) with a time interval of 3 s.

$$\text{NH}_4\text{COO}^- + R,R,N\text{NH} \rightarrow R,R,N\text{COO}^- + R,R,N\text{NH}_4^+$$  \hspace{1cm} (2)

$$\text{NH}_4\text{COO}^- \rightarrow R,R,\text{COOH} \quad \text{Carbamic acid} \quad (3)$$
Among them, the carboxylic acid production, which is the carboxylic acid, can act as an electron donor during the contact electrification with PDMS and becomes positive. Hence, a higher CO$_2$ concentration, which can increase the production of carboxylic acid, will yield a higher $q_1$. However, the decrease of $q_1$ at the CO$_2$ concentration higher than 6250 ppm indicates that carboxylic acid is not the only factor that determines contact electrification upon the surface. A possible reason is that the gaseous CO$_2$ can be trapped on top and infiltrates through the PEI layer without reacting with PEI. As a nonpolar molecule, CO$_2$ (fitted curve) is shown in Figure 5b, and the exhalation, is shown in Figure 5b, and the environment, to 40,000 ppm, which is the CO$_2$ concentration of the ambient 420 ppm, which is the concentration of the ambient environment, as indicated in Figure 5b. The fitting curve indicates that the CO$_2$ peaks at a concentration between 27,000 and 40,000 ppm, which means that the data point of 40,000 ppm is on the declining trend. The reason is the same as the decrease of $q_1$ in static characterization. The excessive amount of nonpolar CO$_2$ molecules covers the surface and reduces the efficiency of contact electrification. An interesting point is that $\Delta q_1$ can recover to the ambient level in the subsequent pulse after applying the CO$_2$ spray even when the concentration is very high. This is because the complexation of CO$_2$ and PEI will inhibit further CO$_2$ infiltration. To the CO$_2$ trapping and reaction can only occur on the PEI surface during a short-term gas spray. Without CO$_2$ diffusing into the PEI internal layer, CO$_2$ can detach from the surface and dissipate very fast. The IR spectra of PEI coated on a molybdenum substrate, which show the change of complexation of CO$_2$ and PEI for the 2000 ppm of CO$_2$ gas concentration and ambient environment gas concentration, are shown in Figure 5e. The black line shows the initial IR spectrum when the chamber is filled with ambient air. Then, the chamber is filled with a 2000 ppm of CO$_2$ gas concentration for 15 s, which is the red line. Then, the chamber is flushed with ambient air again for another 15 s, and the spectrum recovers, which is shown as the blue line. As can be seen, the black and blue lines fully overlap, which indicates a complete recovery. The amplitude of reflectivity at 2.97 $\mu$m was recorded with a 3 s time interval, which is the minimum time duration for scanning the IR spectra, for the entire experiment, as shown in Figure 5f. As indicated in the figure, when the sample was exposed to 2000 ppm of CO$_2$, the normalized reflectivity began to rise and peaked after 15 s. Then, the chamber was flushed with ambient air for another 15 s. The normalized reflectivity immediately began to drop with almost the same rate of increase. This result shows that the CO$_2$–PEI reaction on the surface can be quickly changed by the environment. Since the IR spectra scanning requires at least 3 s, we do not have a chance to further investigate the real recovery time if the gas spray only lasts for 1 s. Considering that in the dynamic CO$_2$ sensing, the gas spray only lasts for 1 s, the time required for full recovery should also be 1 or 2 s. It should be noted that $\Delta q_1$ can also be observed for a CO$_2$ spray at an ambient concentration, which is 420 ppm. In the test, gas was sprayed at a very high flow rate, which is 1000 mL/s. Such high flow rate also increases the chance of contact between CO$_2$ molecules and PEI surface, which generates more CO$_2$ and PEI complexation and increases $\Delta q_1$. This reveals that the mass flow rate should be the real factor that determines $\Delta q_1$.

In summary, $q_1$ and $\Delta q_1$, which are measured during the operation of WATENG, are used to determine RH and the CO$_2$ concentration, respectively. Considering that RH interferes with the performance of triboelectric output, with a complete calibration of $\Delta q_1$ versus CO$_2$ concentration for each RH, as shown in Figure 5b, the WATENG can be used for CO$_2$ sensing for environments with different RH. Meanwhile, because both the upper and lower surfaces of the dielectric layer are used for electrostatic charge coupling, the output energy of the WATENG can be much enhanced compared with TENGs with conventional structure. With the PEI coating, the CO$_2$ sensing is characterized at different RH in a static environment. The sensing range can be up to 6000 ppm. A higher CO$_2$ concentration introduces a nonmonotonous effect and causes a deteriorated sensing result because of the accumulation of excessive CO$_2$ on the surface. A lower RH
leads to a higher triboelectric output, which offers better sensitivity. Hence, for a continuous CO2 sensing application, a desiccant, which is used to lower the RH surrounding environment of WATENG, can enhance the responsivity and sensitivity. The dynamic CO2 sensing of a pulse gas spray is also demonstrated. Compared with the static situation, the sensing range of the dynamic situation can be broadened to 30,000 ppm. The output tends to saturate when the CO2 concentration is higher than 30,000 ppm. In the dynamic testing, the ambient RH can also be measured when the CO2 concentration is a constant value, which is approximately 420 ppm. With the characterization of \( q_1 \) at a CO2 concentration of 420 ppm, this dynamic testing manner is useful for the environments with various RH. Thus, the structure of WATENG enables itself as a self-powered amenity sensor.

ASSOCIATED CONTENT

S Supporting Information

The Supporting Information is available free of charge on the ACS Publications website at DOI: 10.1021/acsnano.7b05213.

S1: Detailed fabrication process, optical and SEM images of the WATENG. S2: Testing chamber to control the humidity, CO2 concentration for static characterization. S3: Testing setup for obtaining IR spectra. S4: Calibration of \( q_1 \) at ambient CO2 concentration (420 ppm) with different RH (PDF)

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Notes

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