

<b>Wednesday, September 25</b>									
Keynote I: 8:30 - 9:30, Auditorium <b>The Changing Face of Adaptive Control</b> K.S. Narendra, Yale University									
Tea Break: 9:30 - 10:00									
Track	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	<b>5</b>	<b>6</b>	<b>7</b>	<b>8</b>	<b>9(P)</b>
Room	307	308	309	310	311	312	313	314	305
WA 10:00 – 12:00	<b>Network Control</b>	<b>Linear Control</b>	<b>Adaptive Control I</b>	<b>Robotics and Motion Control I</b>	<b>Robust Control I</b>	<b>Fuzzy and Neural System I</b>	<b>PID Control</b>	<b>Nonlinear Control I</b>	<b>Intelligence and Adaptation</b>
Lunch: 12:00 – 13:30									
WM 13:30 – 15:30	<b>Iterative Learning Control</b>	<b>Multivariable Control</b>	<b>Adaptive Control II</b>	<b>Robotics and Motion Control II</b>	<b>Robust Control II</b>	<b>Fuzzy and Neural System II</b>	<b>Predictive Control</b>	<b>Nonlinear Control II</b>	<b>Linear and Nonlinear Control</b>
Tea Break: 15:30 – 16:00									
WP 16:00 – 18:00	<b>Trends in Nonlinear Control</b>	<b>Optimal Control and Optimization I</b>	<b>Identification and Estimation I</b>	<b>Robotics and Motion Control III</b>	<b>Robust Control III</b>	<b>Fuzzy and Neural Systems III</b>	<b>Process and Chemical Systems I</b>	<b>Nonlinear Control III</b>	<b>Control Systems</b>

**Thursday, September 26**

Keynote II: 8:30 - 9:30, Auditorium

**Why Control and Biology Now?: From Cells to Brain**

Hidenori Kimura, The University of Tokyo

Tea Break: 9:30 - 10:00

Track	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	<b>5</b>	<b>6</b>	<b>7</b>	<b>8</b>	<b>9(P)</b>
Room	307	308	309	310	311	312	313	314	305
TA 10:00 – 12:00	<b>Further Development of Coefficient Diagram Method</b>	<b>Optimal Control and Optimization II</b>	<b>Identification and Estimation II</b>	<b>Robotics and Motion Control IV</b>	<b>System Theory I</b>	<b>Fuzzy and Neural Systems IV</b>	<b>Fault Detection</b>	<b>Control Education</b>	<b>Robust Control and Robotics</b>

Lunch: 12:00 – 13:30

TM 13:30 – 15:30	<b>Financial Systems</b>	<b>Optimal Control and Optimization III</b>	<b>Identification and Estimation III</b>	<b>Mechatronics</b>	<b>System Theory II</b>	<b>GA and Evolutionary Computing</b>	<b>Hybrid and Supervisory Systems</b>	<b>Advanced Application of Coefficient Diagram Method</b>	<b>Industrial Systems</b>
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Tea Break: 15:30 – 16:00

Banquet: 19:30 – 21:30

<b>Friday, September 27</b>								
Keynote III: 8:30 - 9:30, Auditorium								
<b>Why not FIR Filters for Control: FIR Filters for State Space models</b>								
Wook Hyun Kwon, Seoul National University								
Tea Break: 9:30 - 10:00								
Track	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	<b>5</b>	<b>6</b>	<b>7</b>	<b>8</b>
Room	307	308	309	310	311	312	313	314
FA 10:00 – 12:00	<b>Further Development of Coefficient Diagram Method</b>	<b>Simulation and Control CAD</b>	<b>Signal Processing</b>	<b>Aerospace</b>	<b>System Theory III</b>	<b>Intelligent and Learning Control</b>	<b>Process and Chemical Systems II</b>	<b>Nonlinear Control IV</b>
Farewell Lunch: 12:00 – 13:30								